



Computer Graphics

Rendering Pipeline

Teacher: A.prof. Chengying Gao(高成英)

E-mail: mcsqcy@mail.sysu.edu.cn

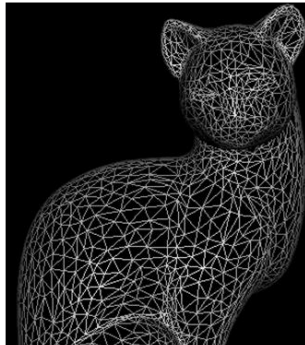
School of Data and Computer Science



Outline

- **Computer Graphics System**
- Physical Imaging System
- Graphics Rendering Pipeline

Modeling
(Creating 3D Geometry)

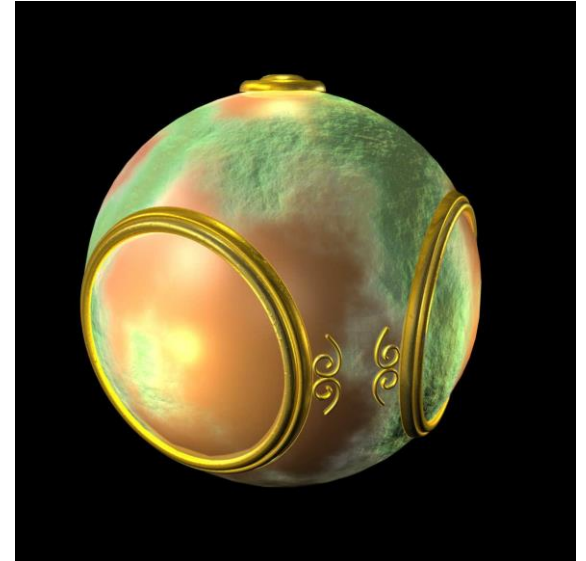


Rendering
(Creating, shading images from geometry, lighting, materials)



Example

- Where did these images come from?

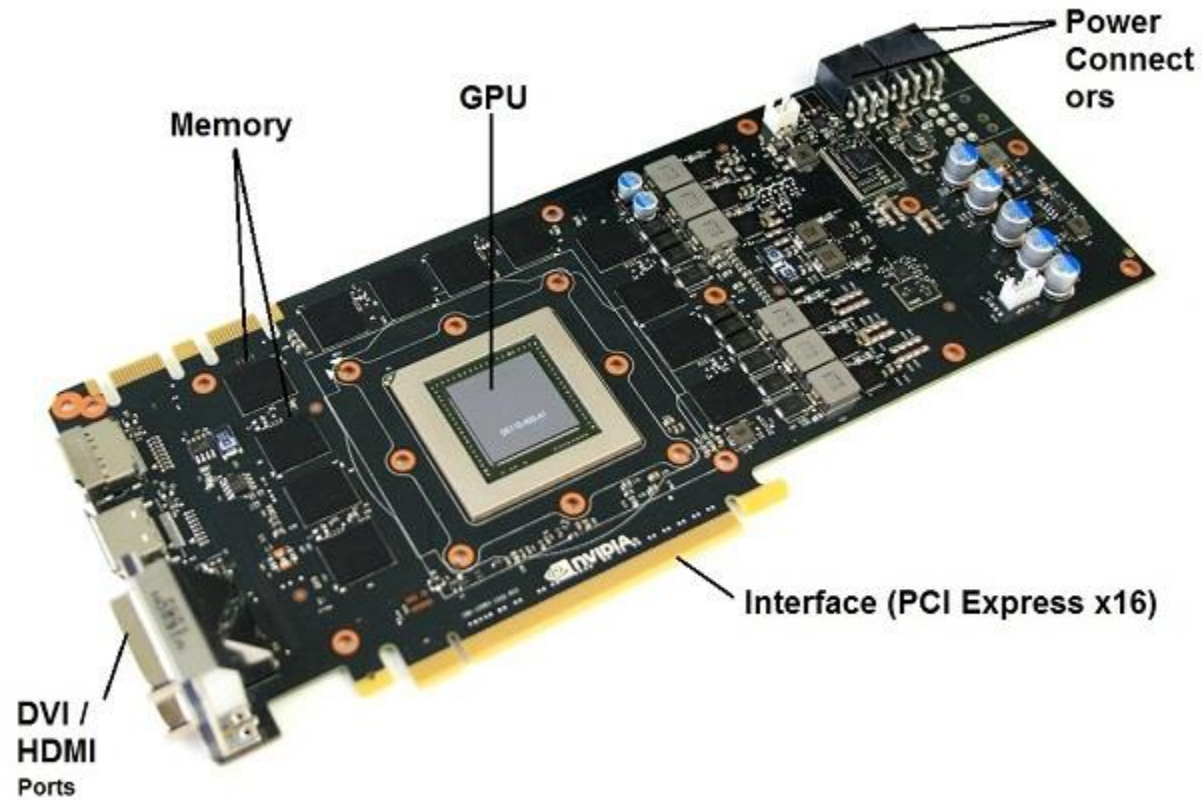


- What hardware/software did we need to produce it?
 - Software: Maya for modeling and rendering but Maya is built on top of OpenGL
 - Hardware: PC with graphics card for modeling and rendering

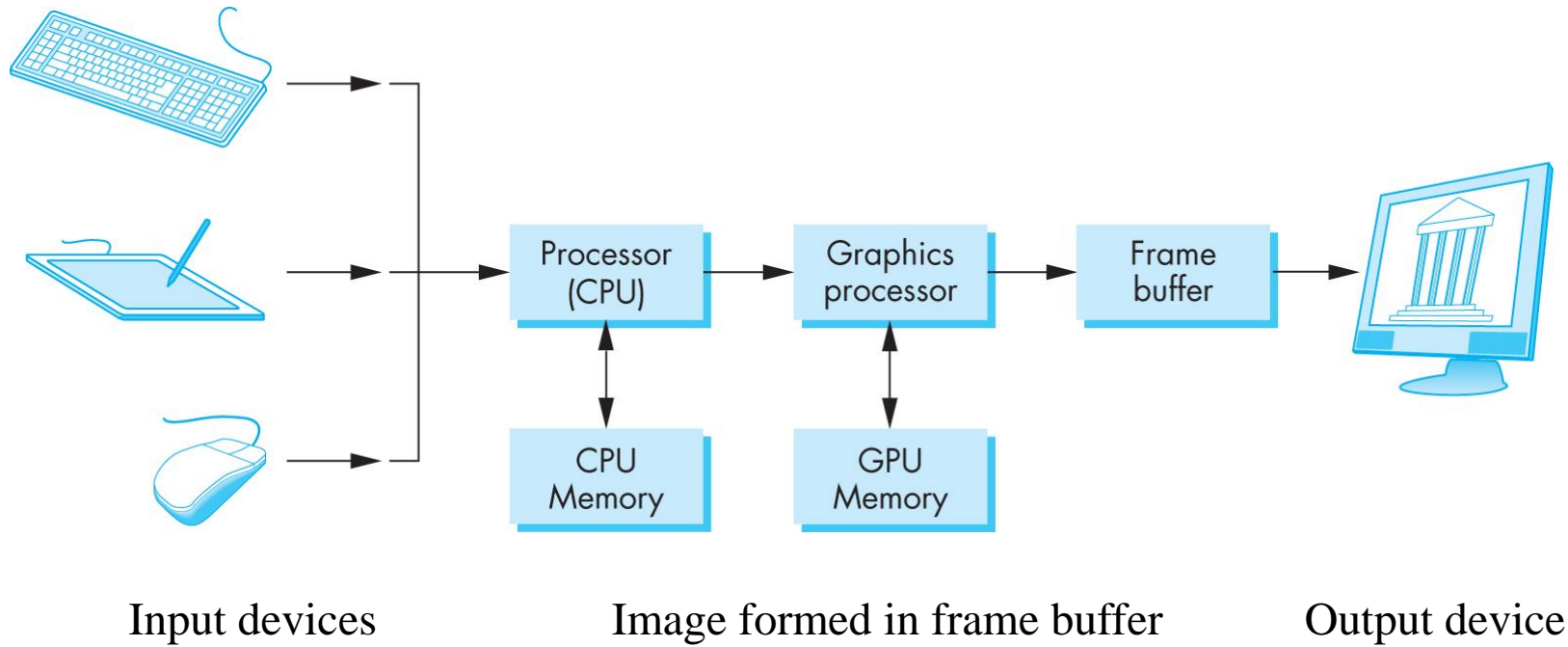
Software – Autodesk Maya



Hardware - display card



A computer graphics system



Angel and Shreiner: Interactive Computer Graphics 6E © Addison-Wesley 2012



Input: Consumer devices

GRAPHIC|S

G|RAPHICS



Input: Image & video



The modern era of easy photography



Better photography in a simple way

\$ 5000



\$ 5



Mobile phone camera

Can these two ever be equally good at taking pictures?

Better photography in a simple way



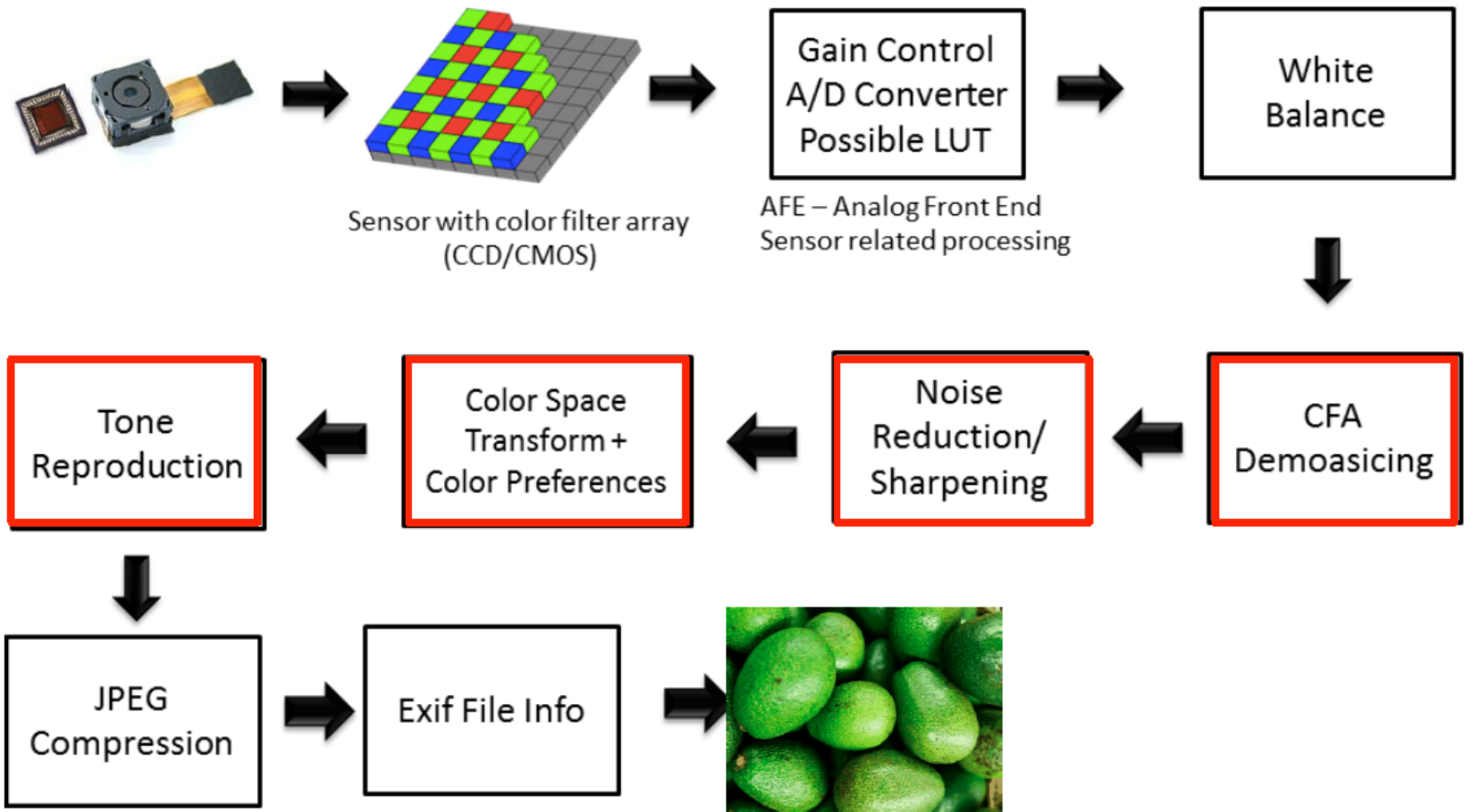
iPhone 3GS



Canon EOS 5D Mark II



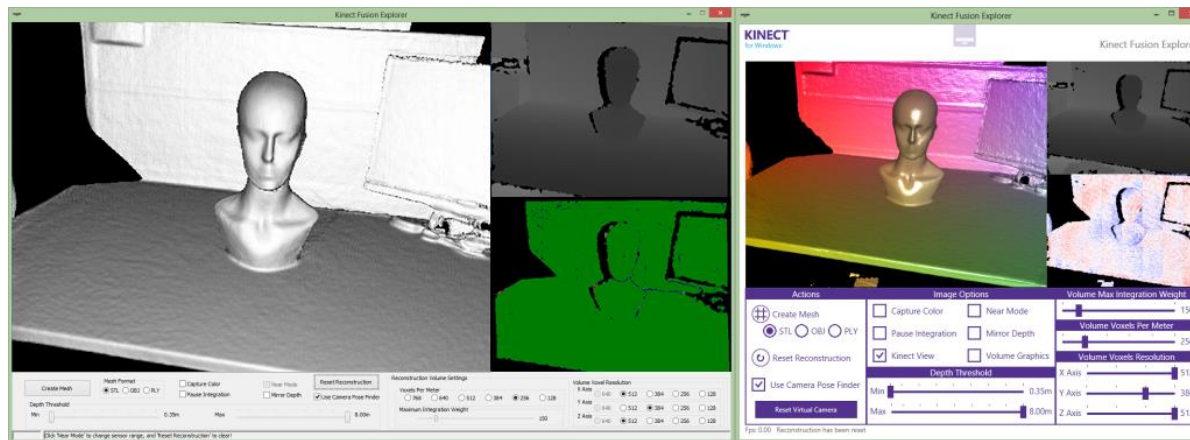
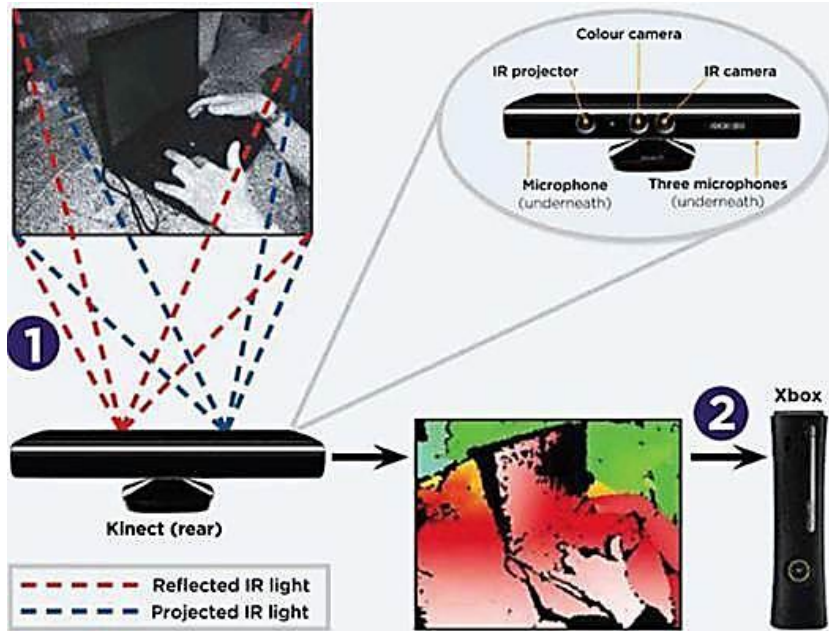
A standard model for imaging pipeline



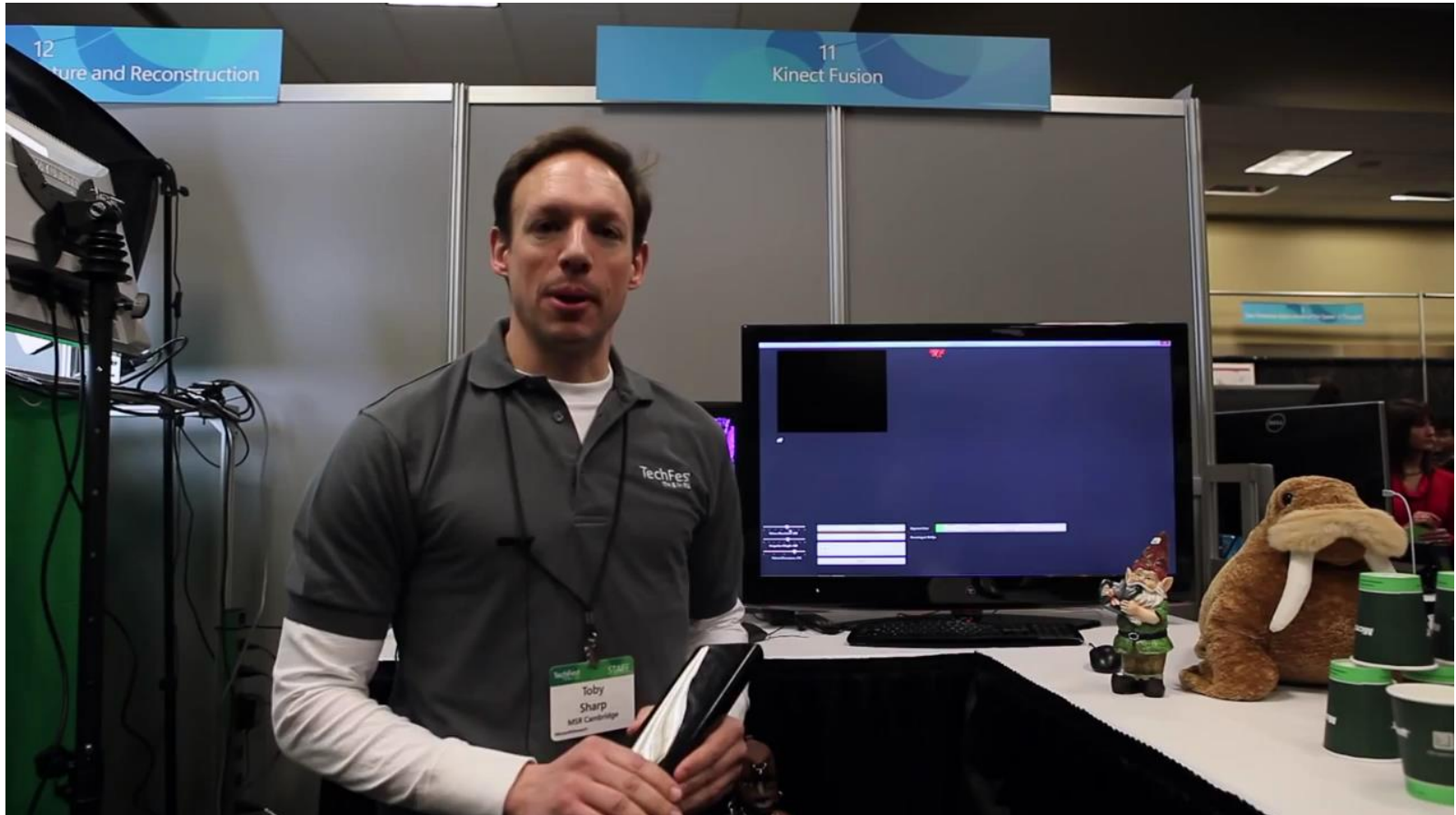
Input: Shape



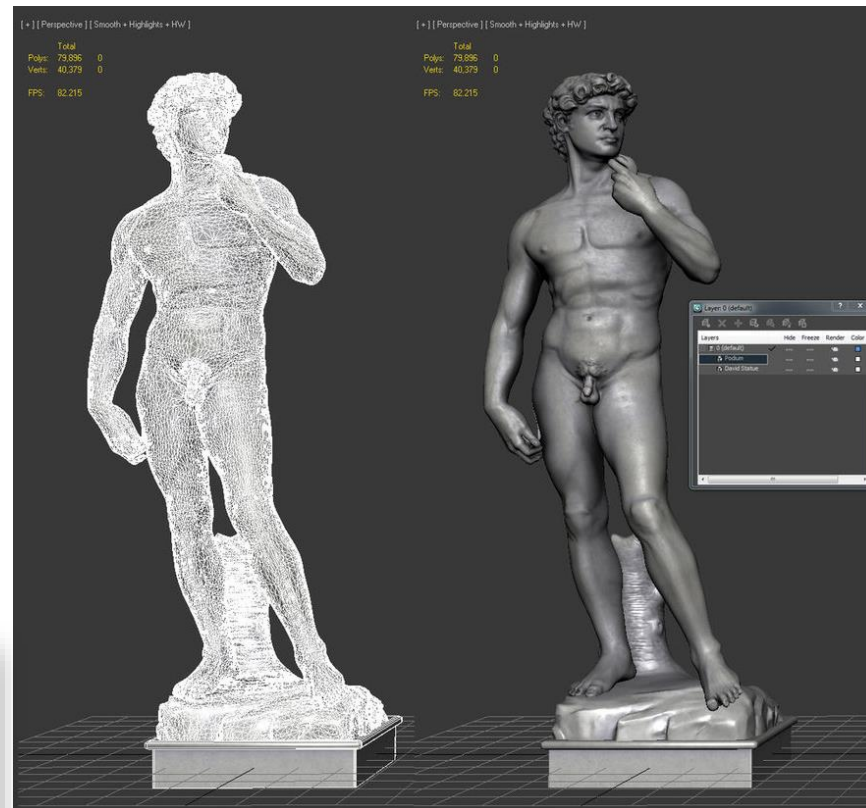
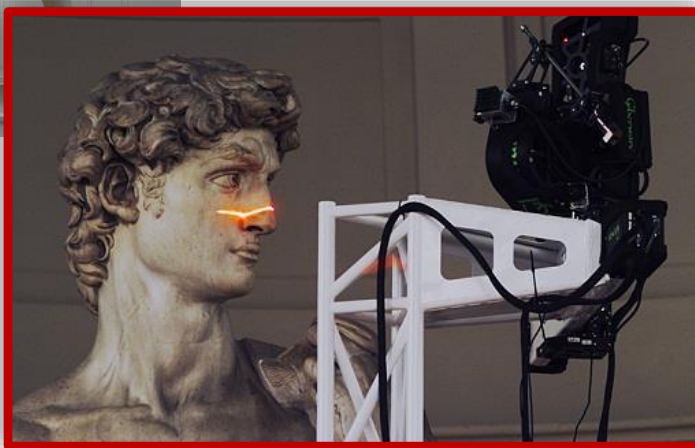
Kinect Fusion



Shapes from Kinect Fusion



3D Scanning



Desktop 3D scanner



MakerBot® Digitizer™
DESKTOP 3D SCANNER

Getting Started With Your First Scan



Input: Specialized devices



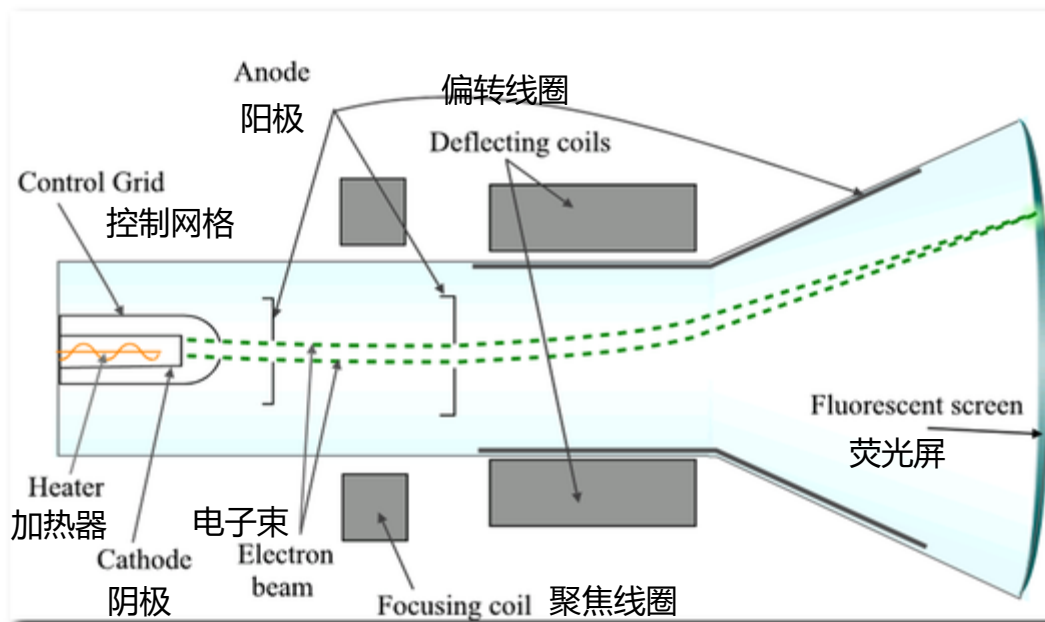
What about the output device?



Display Devices

- Cathode Ray Tube (CRT)

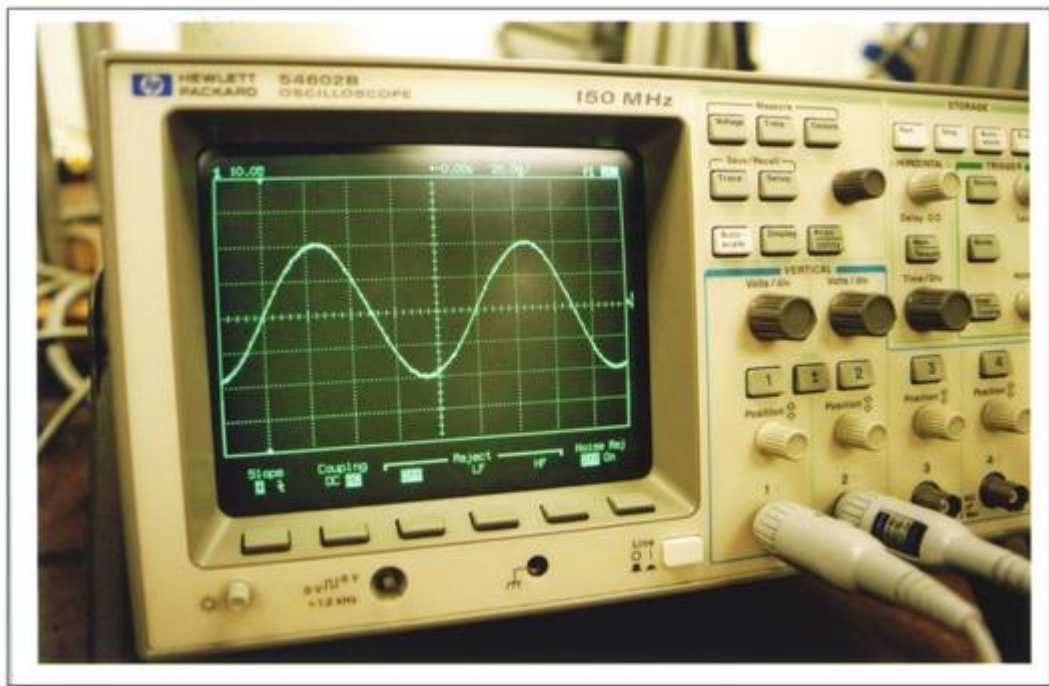
- CRT is a vacuum tube (电子管) containing one or more electron guns, and a phosphorescent screen (荧光屏) used to view images.



Karl Ferdinand Braun, 1897
Image courtesy of Wikipedia

Display Devices

- Vector Displays



HP Oscilloscope



Asteroids, 1979 (行星游戏)



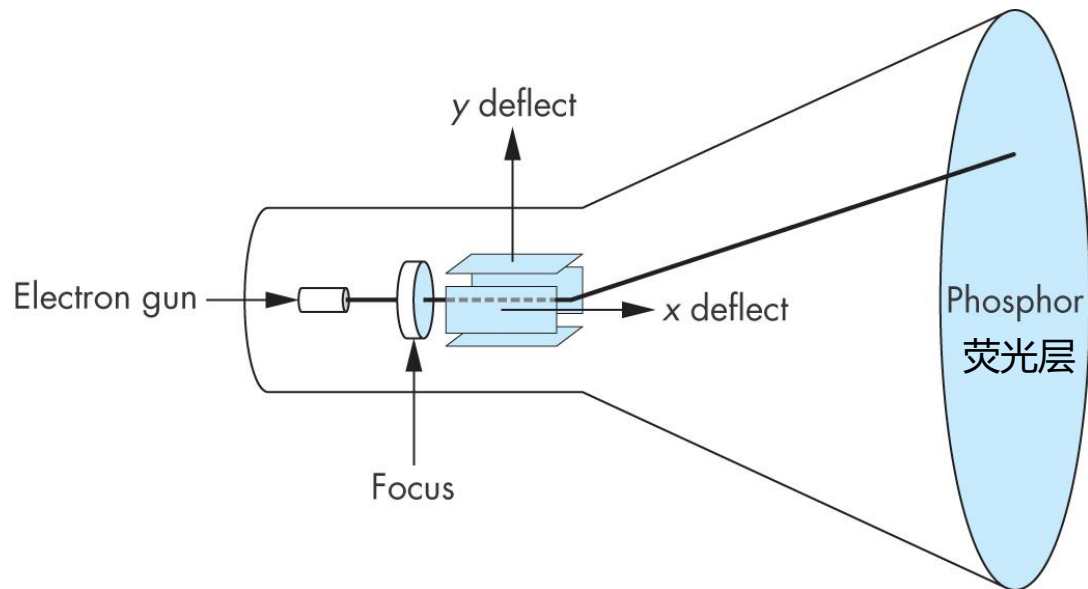
Star Wars, 1983 (星球大战)



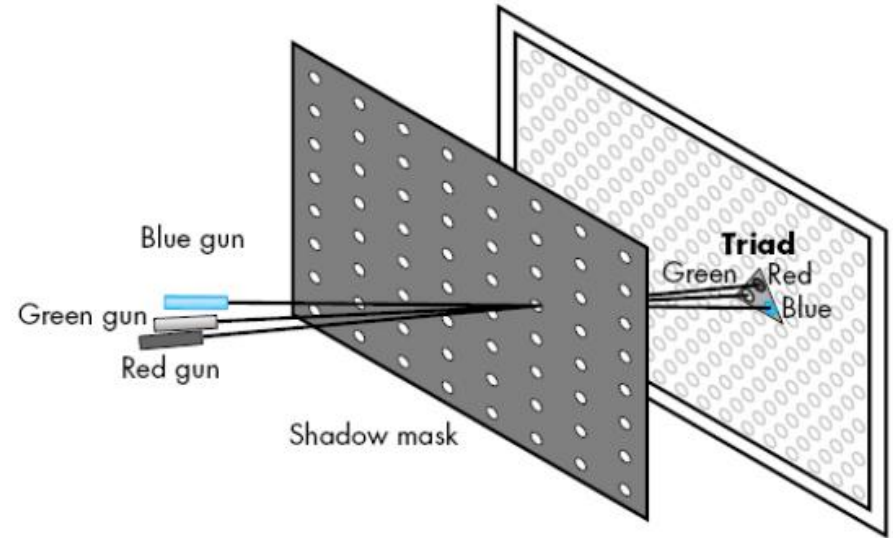
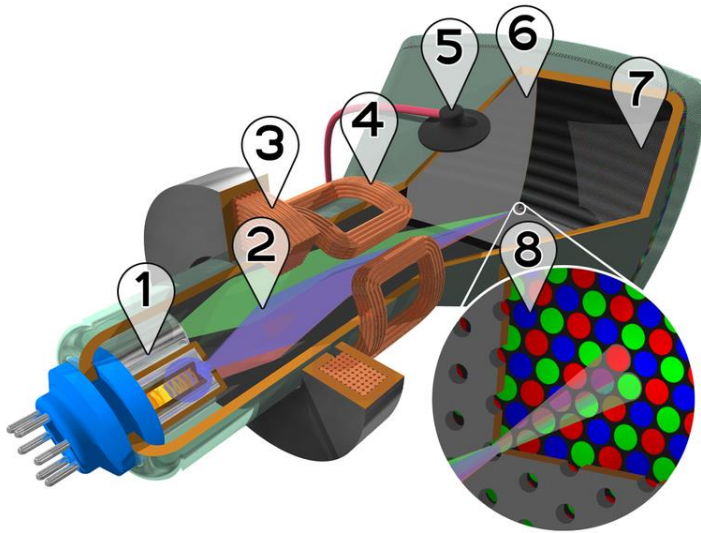
Display Devices

- Raster Display Devices (光栅显示器)

- The refresh type raster scan display : Get the pixels from the frame buffer individually and corresponding location on the screen display.
- Refresh Rate: 刷新率
- Interlaced scan, Non-Interlaced or Progressive scan: 逐行扫描和隔行扫描



Color CRT display

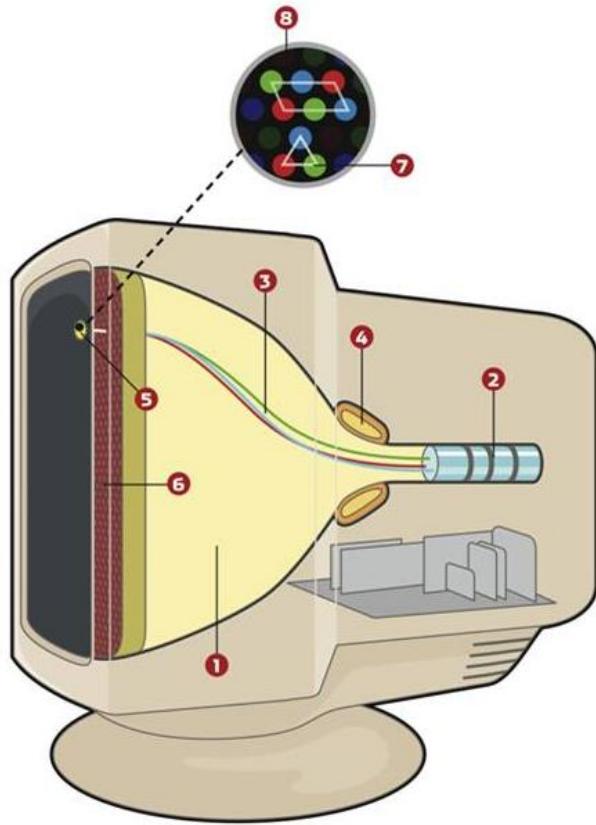


Cutaway rendering of a color CRT:

1. Three electron guns (for red, green, and blue phosphor dots)
2. Electron beams
3. Focusing coils
4. Deflection coils
5. Anode connection
6. Mask for separating beams for red, green, and blue part of displayed image
7. Phosphor layer with red, green, and blue zones
8. Close-up of the phosphor-coated inner side of the screen



Color CRT display



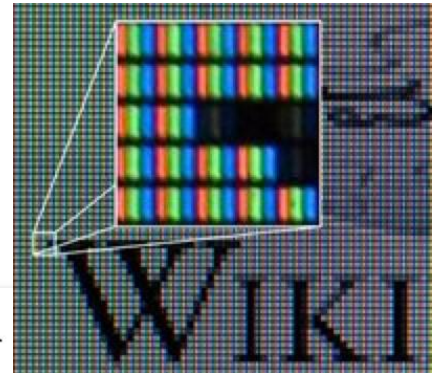
Display Devices

- **Flat-panel monitors**

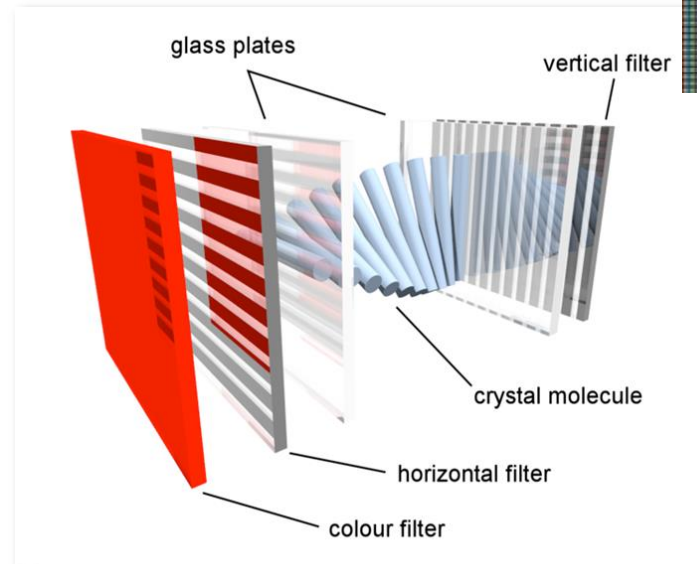
- LED (light-emitting diodes): 发光二极管
- LCD (liquid-crystal displays): 液晶显示器
- Plasma panels: 等离子显示器

- **Advantages:**

- low consumption
- small radiation
- flicker free
- **No geometric distortion**

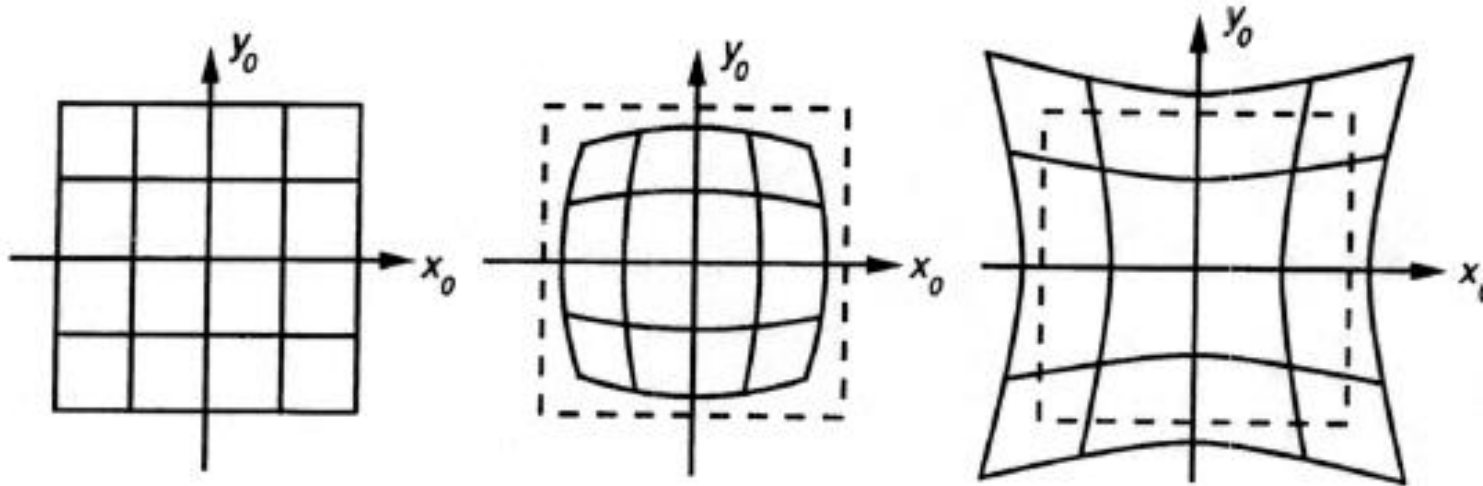


Close-up of pixels on an LCD display



A single subpixel of an LCD display

Geometric distortion in display monitor



No Distortion

无失真

Barrel Distortion

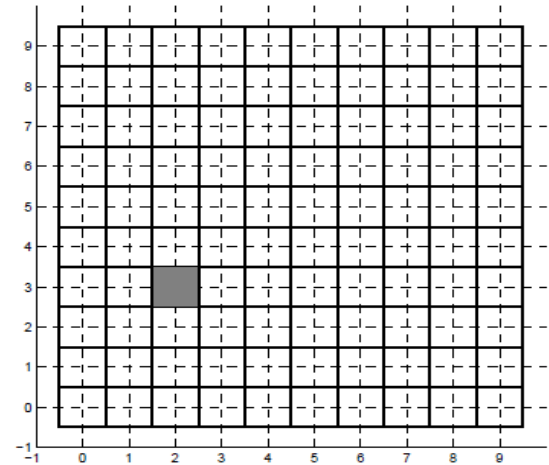
桶形失真

Pincushion Distortion

枕形失真

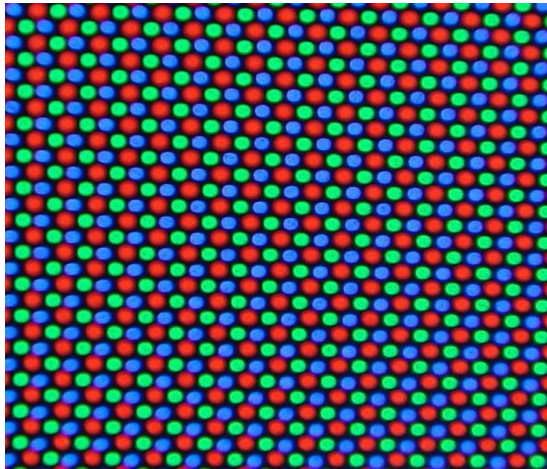
Modeling an image

- Model a one-channel $m \times n$ image as the function $u(i, j)$
 - Maps pairs of integers (pixel coordinates) to real numbers
 - i and j are integers such that $0 \leq i < m$ and $0 \leq j < n$
- Associate each pixel value $u(i, j)$ to small area around display location with coordinates (i, j)
- A pixel here looks like a square centered over the sample point, but it's just a scalar value and the actual geometry of its screen appearance varies by device
 - Roughly circular spot on CRT
 - Rectangular on LCD panel

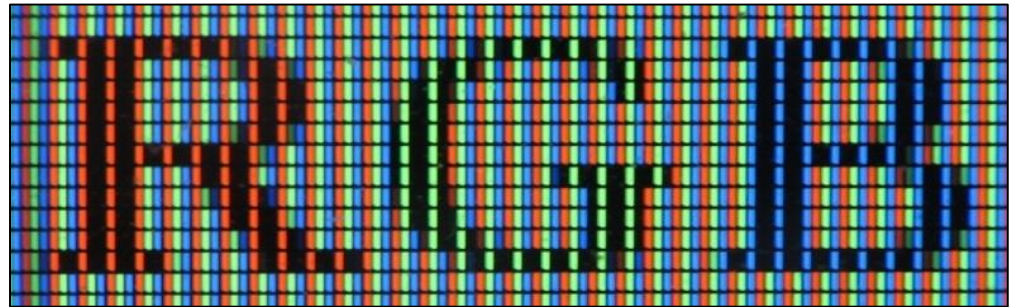


Pixels

- Pixels are point samples
- Point samples reconstructed for display (often using multiple subpixels for primary colors)



Close-up of a CRT screen



Close-up of an LCD screen

Frame buffer

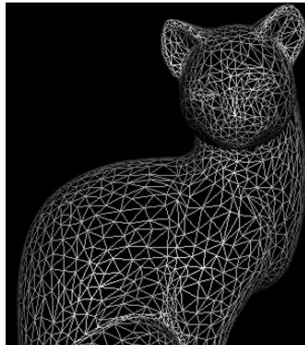
- Frame buffer (帧缓冲区): a buffer that stores the contents of an image pixel by pixel
- Resolution (分辨率): the number of pixels per square inch on a computer-generated display
- Rasterization (光栅化)
- Graphics Processing Units (GPU, 图形处理器)



Outline

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- **Physical Imaging System**
- Graphics Rendering Pipeline

Modeling
(Creating 3D Geometry)

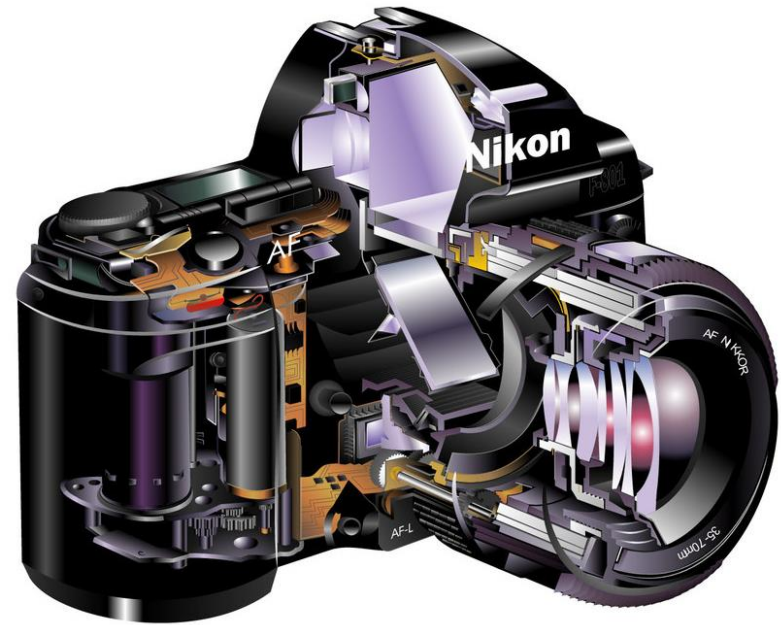
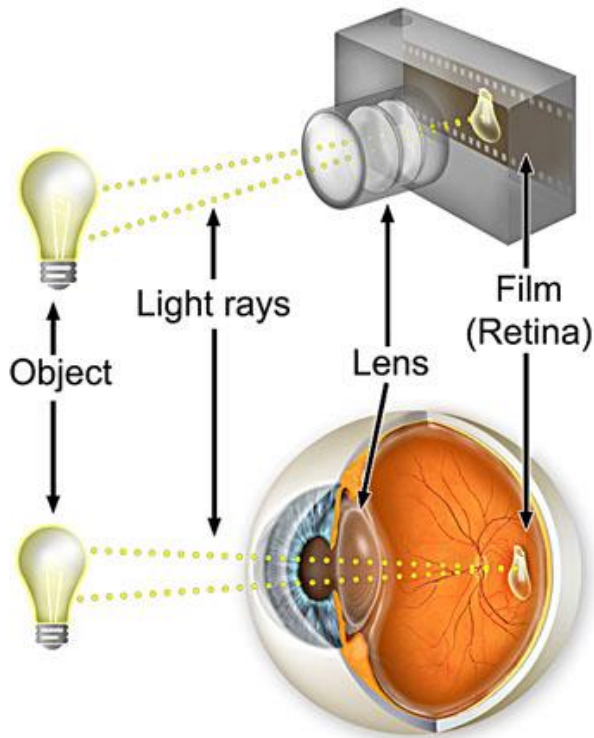


Rendering
(Creating, shading images from geometry, lighting, materials)

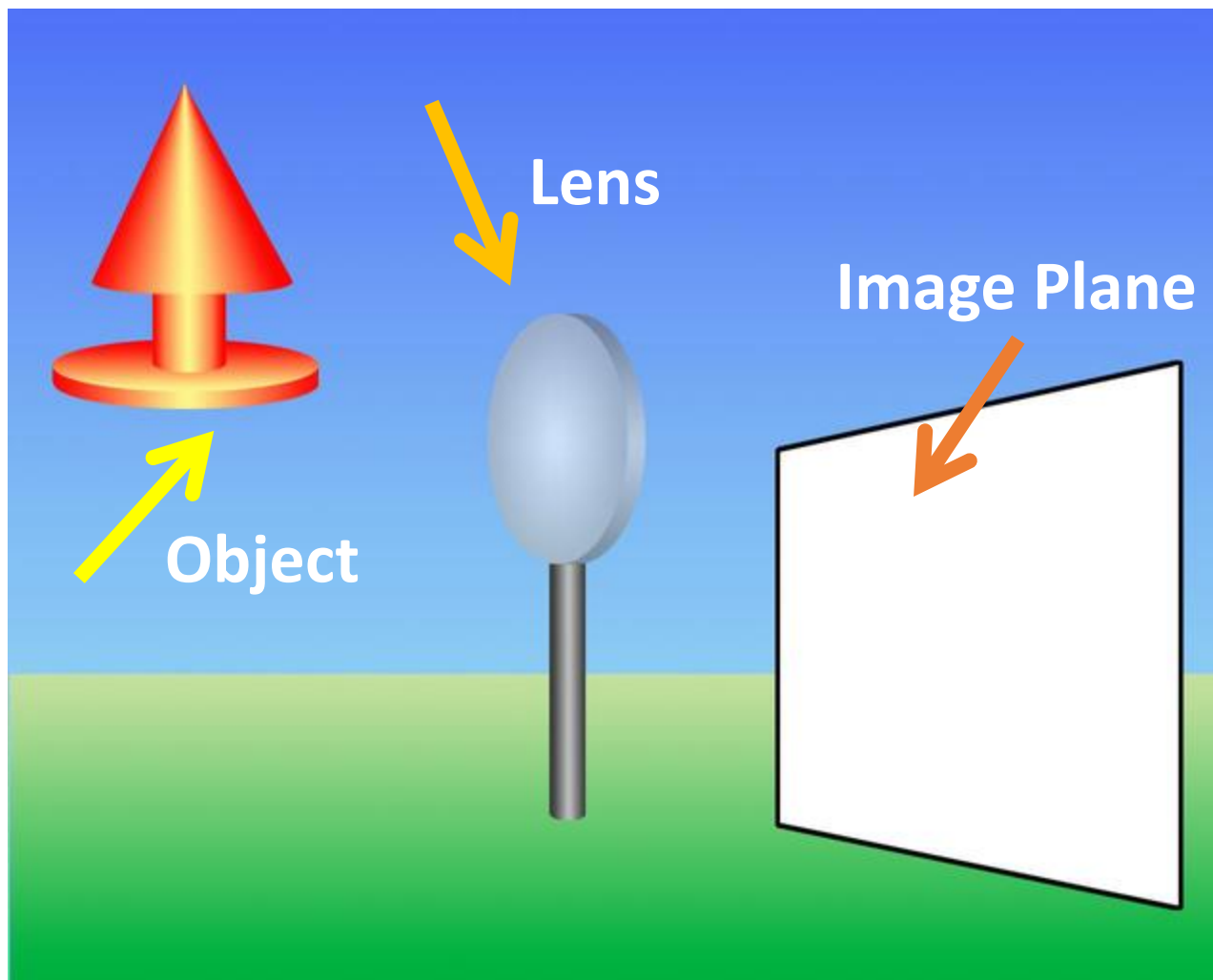


Physical Imaging System

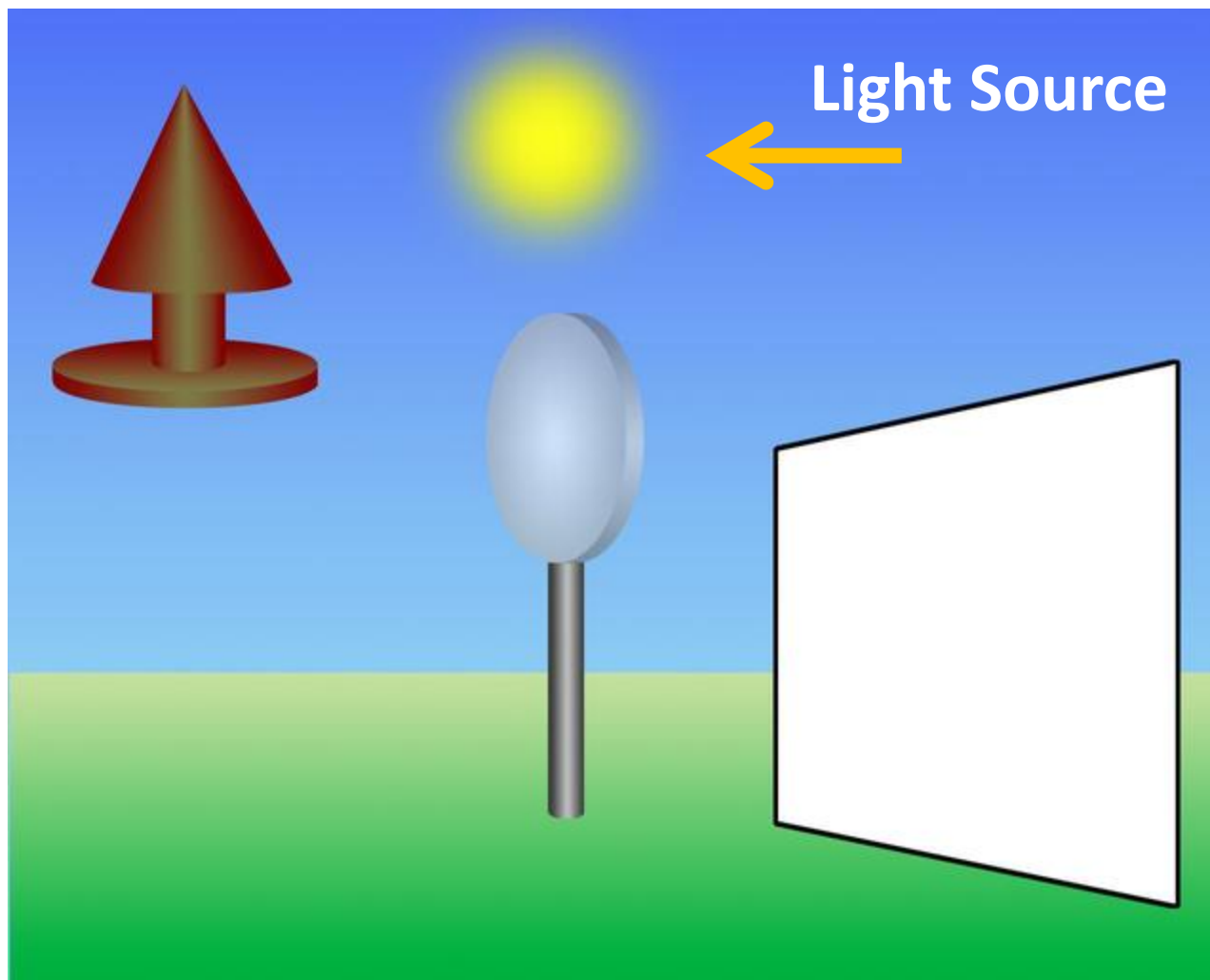
- Eye(biology)
- Camera: film (chemistry),digital (physical + digital)



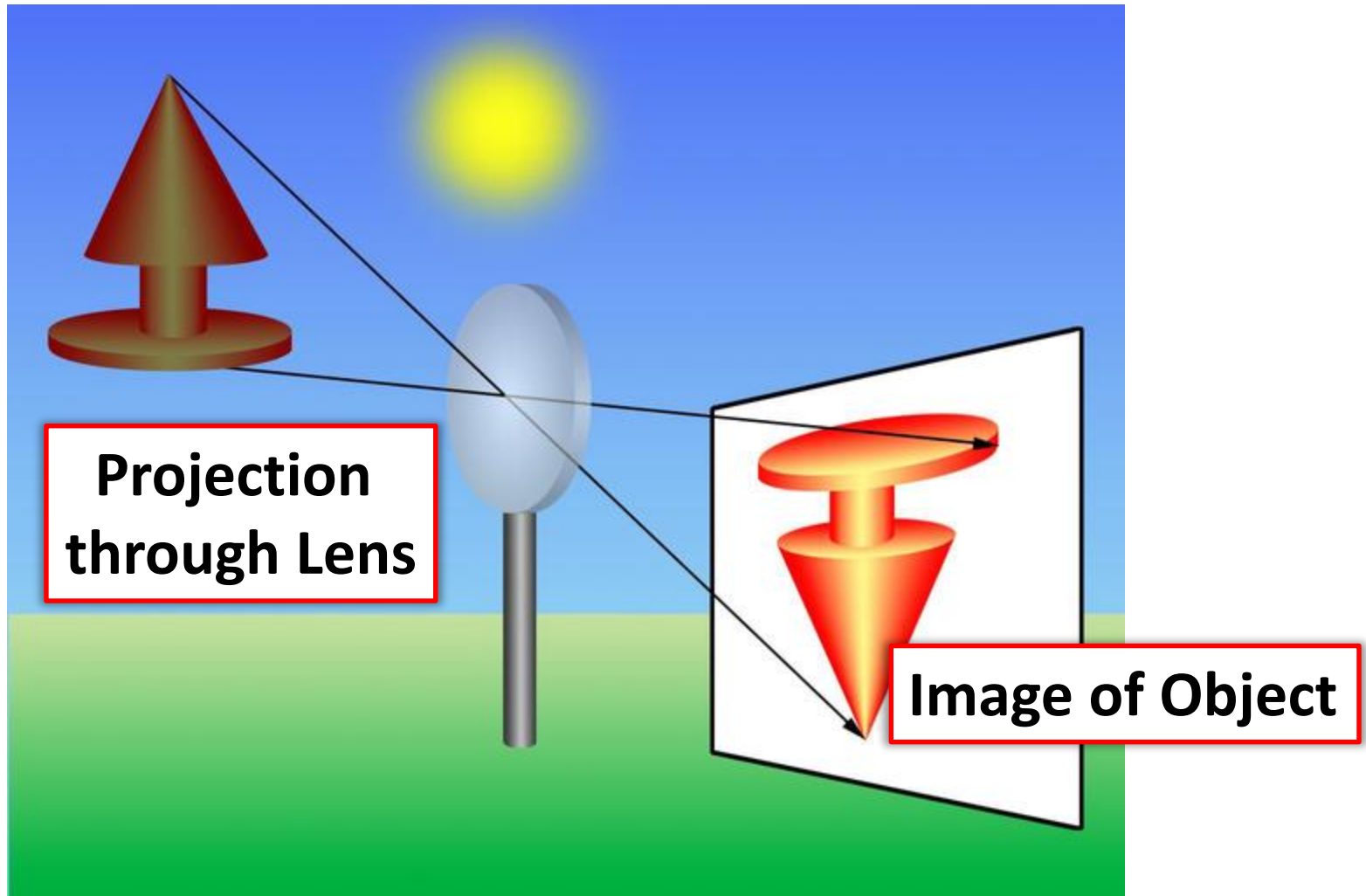
Imaging Principle



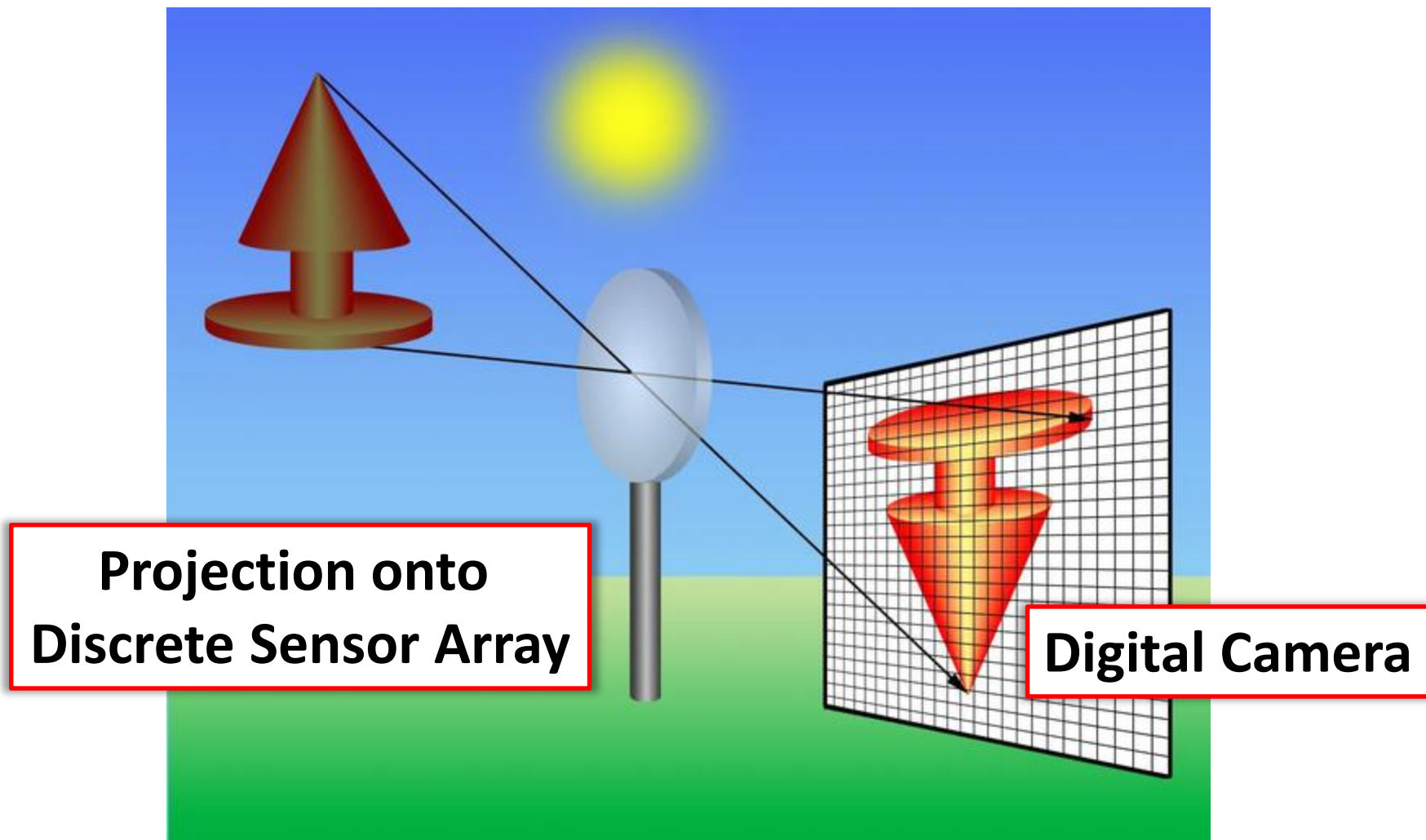
Imaging Principle



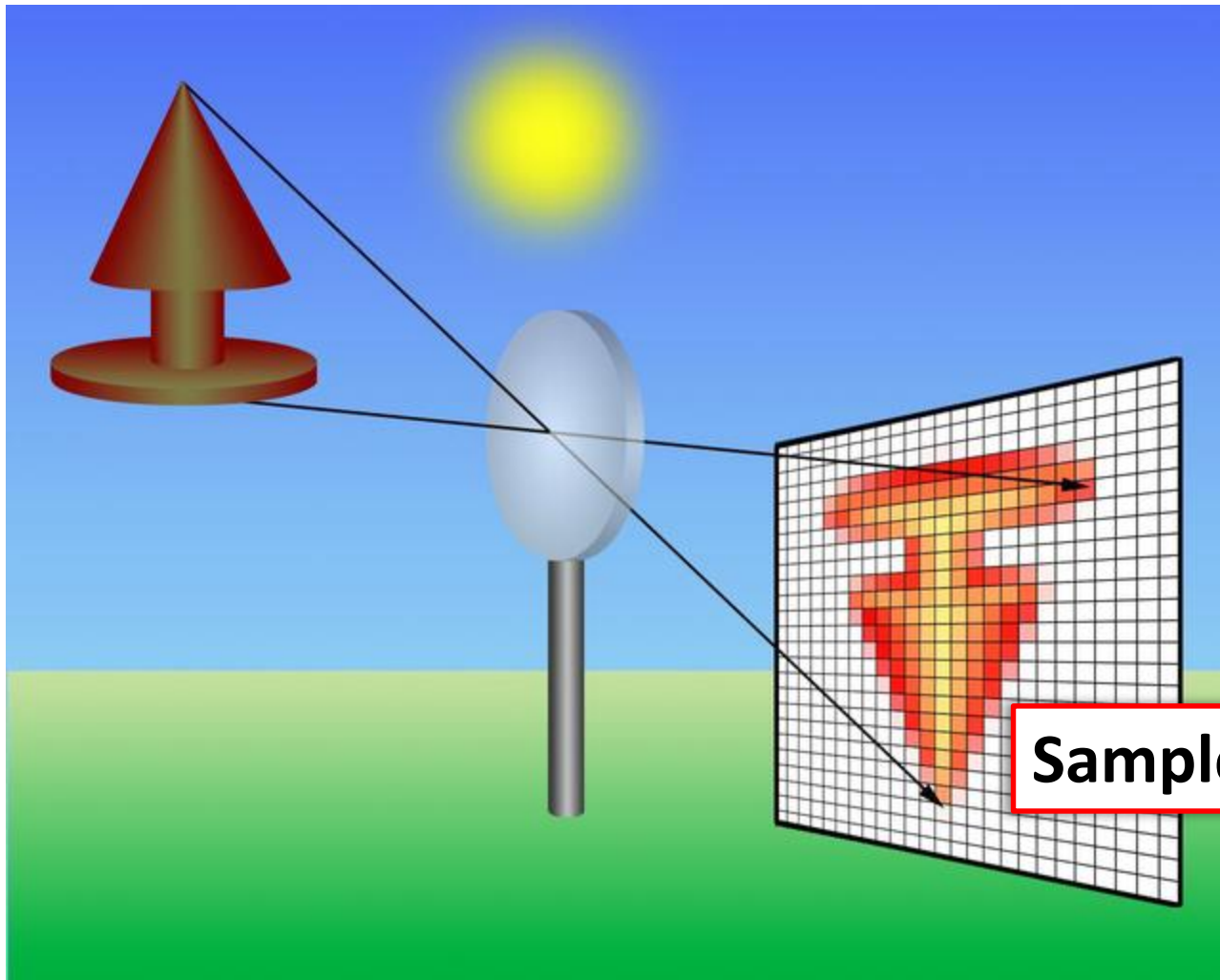
Imaging Principle



Imaging Principle

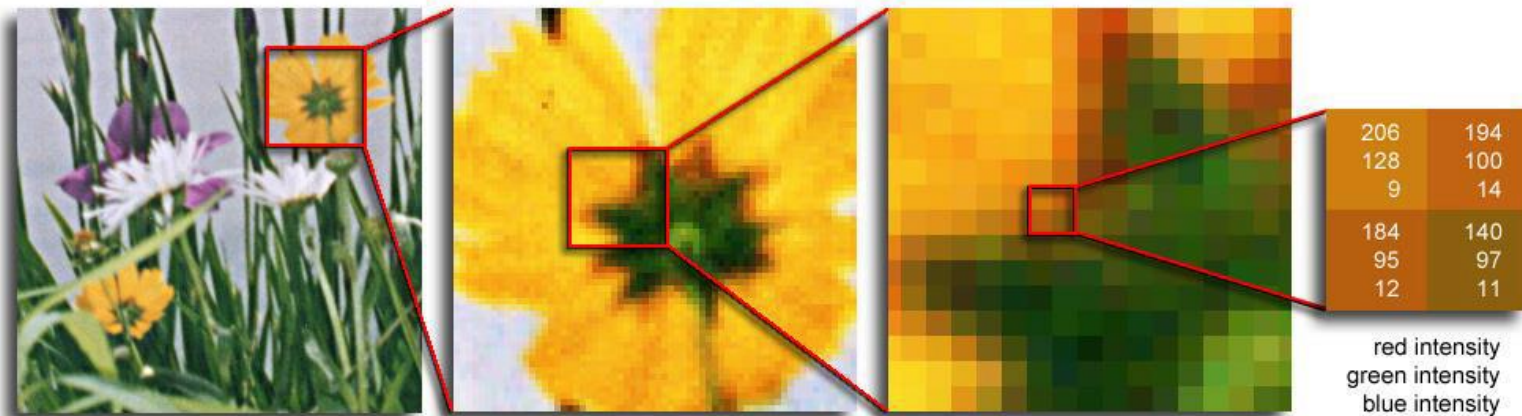


Imaging Principle

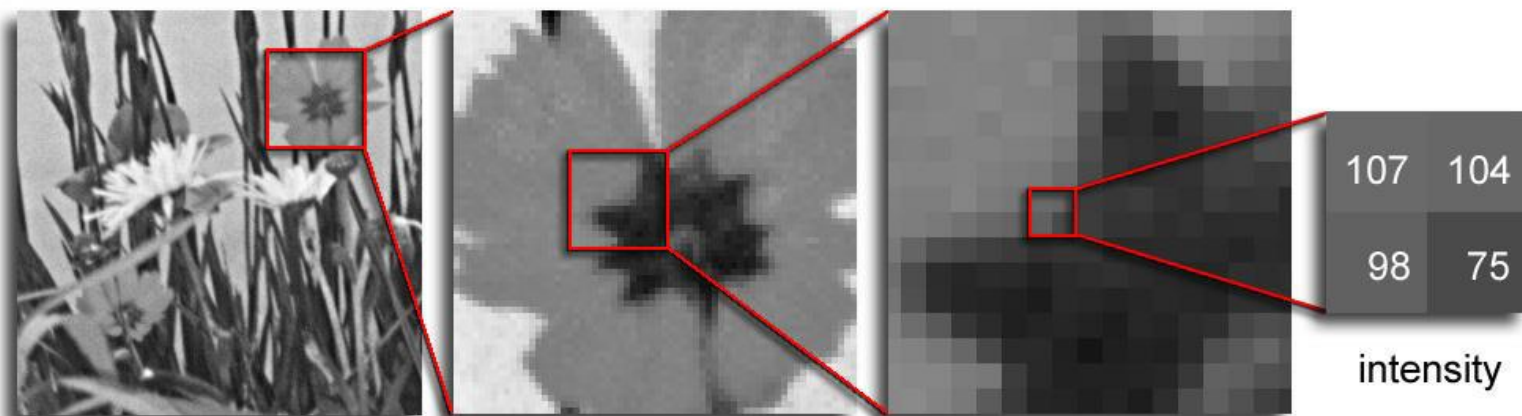


Digital Image

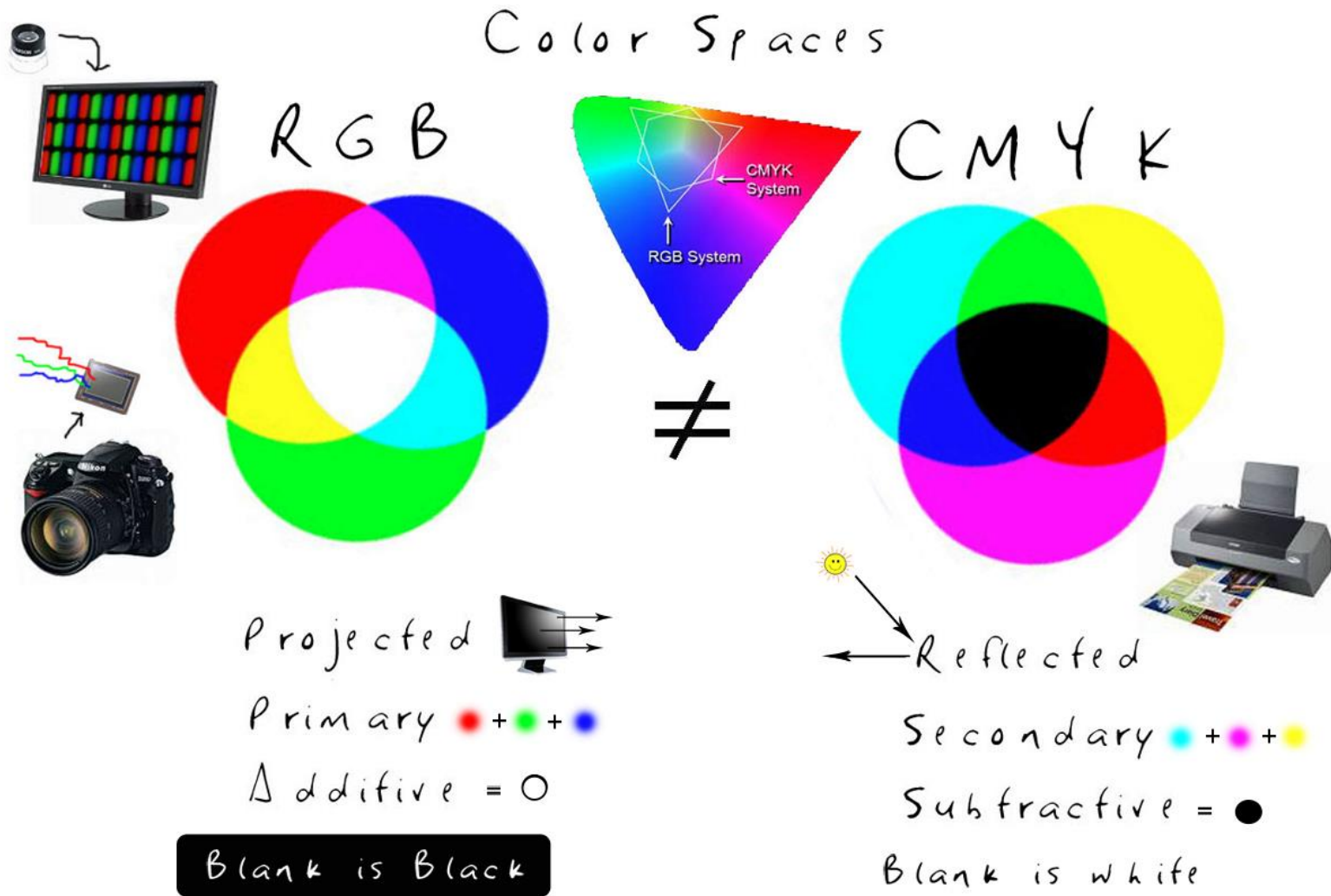
**Color
Image**



**Grey
Image**

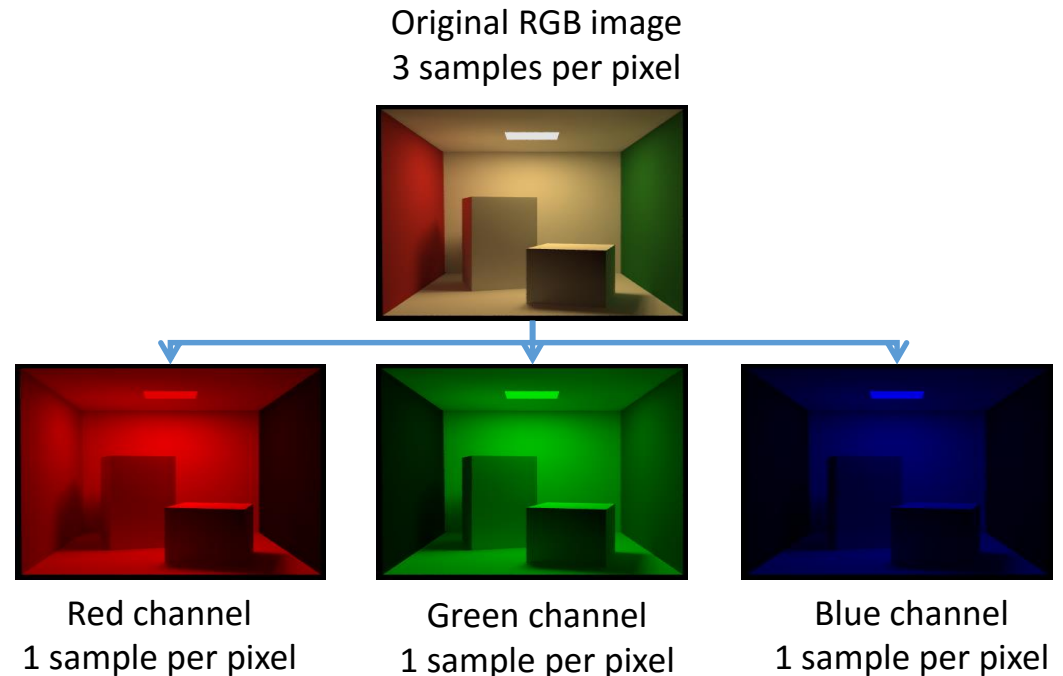


Color Space



What is a channel?

- A channel is all the samples of a particular type
- RGB is a common format for image channels
 - Easy to implement in h/w
 - Corresponds approximately to human visual system anatomy (specialized “R, G, and B” cones)
 - Samples represent the intensity of the light at a point for a given wavelength (red, green, or blue)
- The R channel of an image is an image containing just the red samples



The alpha channel

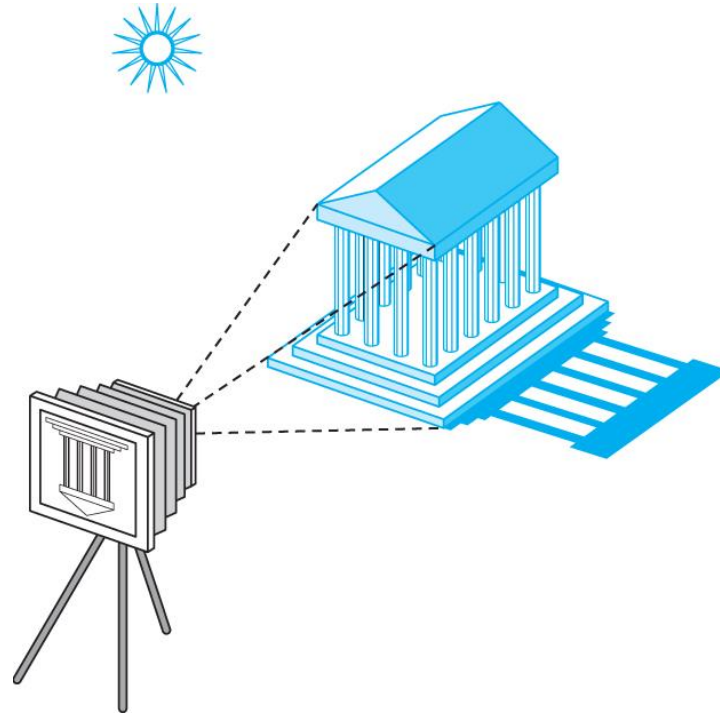
- In addition to the R, G, and B channels of an image, add a fourth channel called α (transparency/opacity/translucency)
- Alpha varies between 0 and 1
 - Value of 1 represents a completely opaque pixel, one you cannot see through
 - Value of 0 is a completely transparent pixel
 - Value between $0 < \alpha < 1$ determines translucency
- Useful for blending images
 - Images with higher alpha values are less transparent
 - Linear interpolation ($\alpha X + (1 - \alpha)Y$) or full Porter-Duff compositing algebra



The orange box is drawn on top of the purple box using $\alpha = 0.8$

Image Synthetic Element

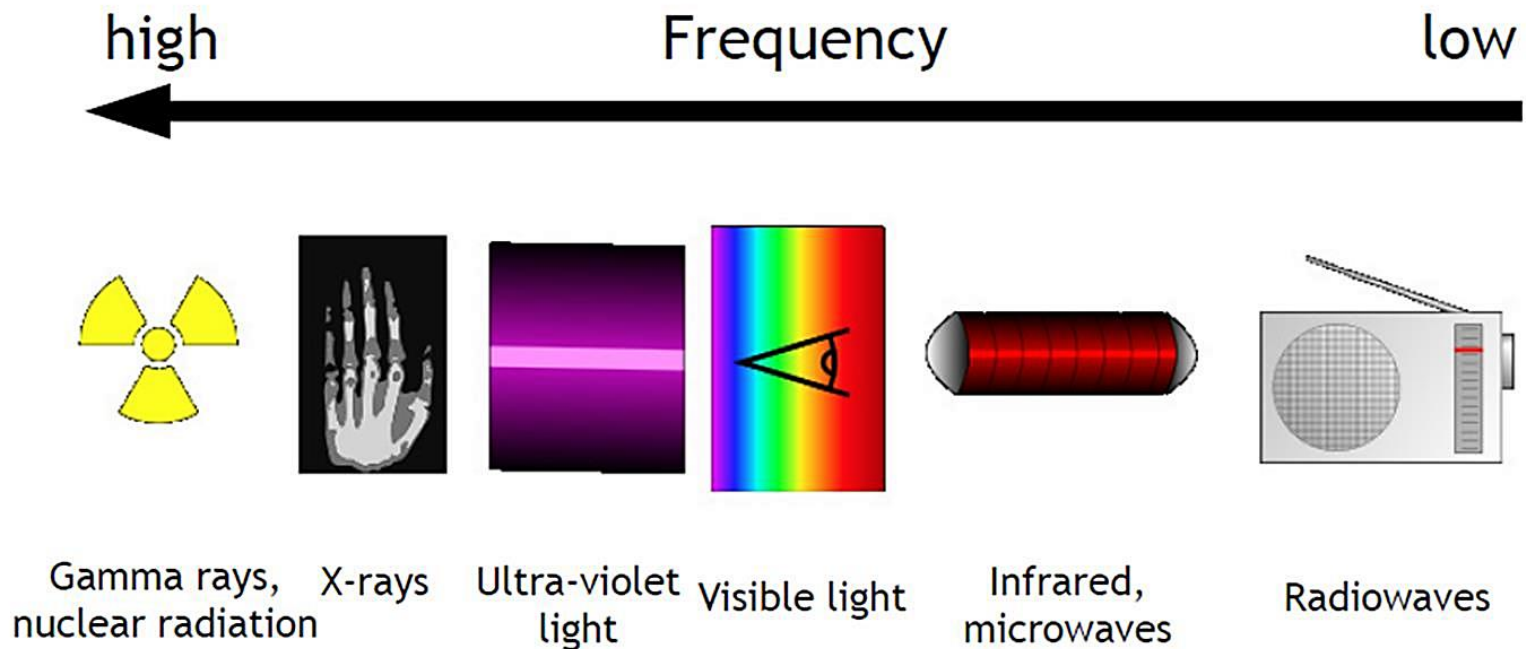
- Object
- Observer
- Light



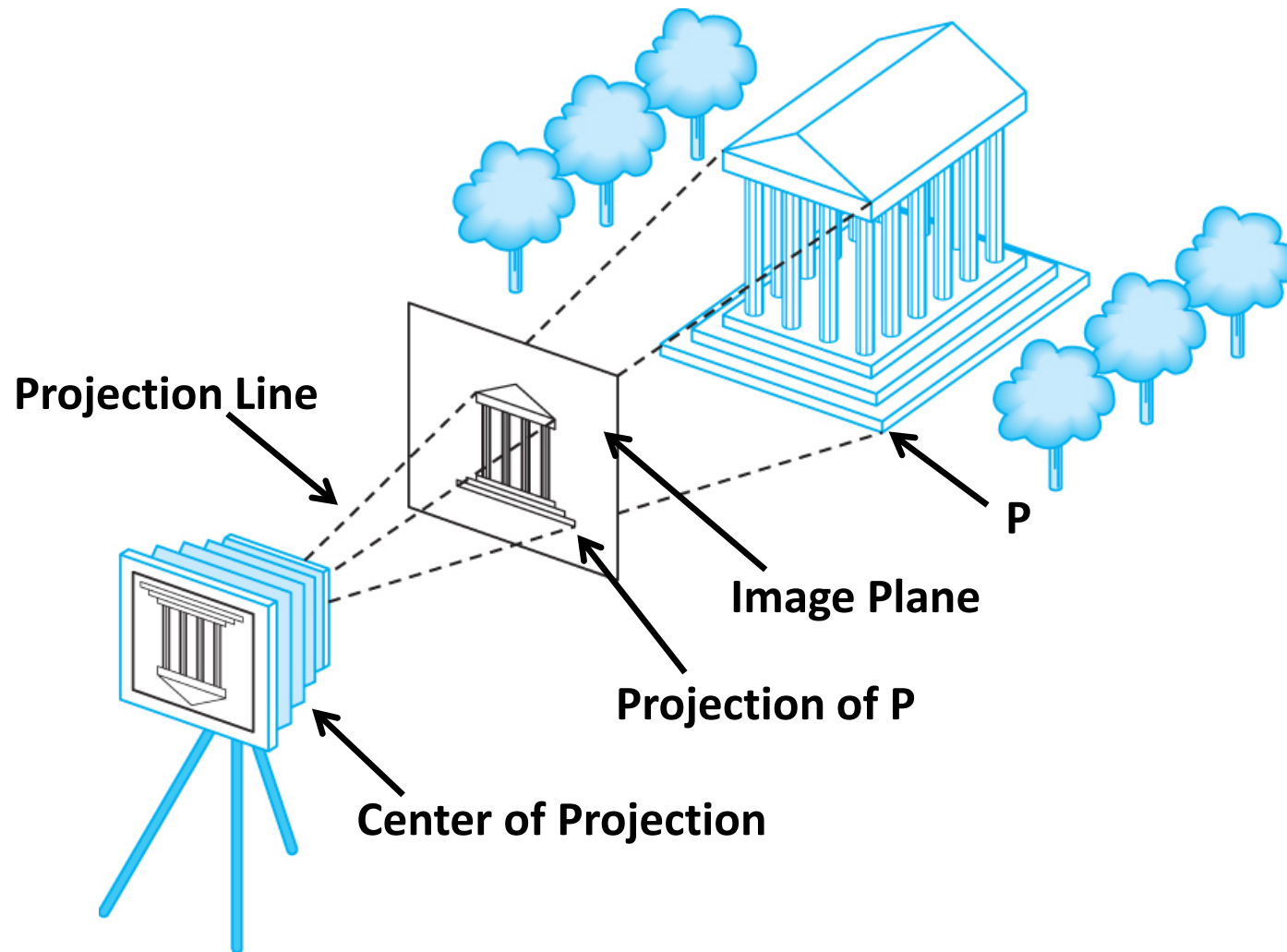
- Properties of Light, material: To determine the effect of light on the object

Light---Visible Light

- Light is a part of electromagnetic wave, it is a wave.
- It' visible range: between 350nm and 780nm
 - ▶ Different frequencies



Synthetic camera model



Advantages of Synthetic camera model

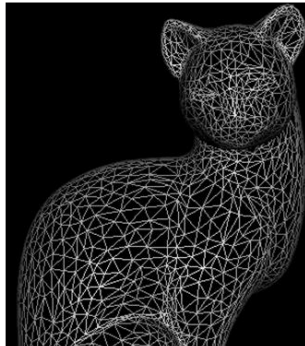
- Object (物体), Observer (观察者) and light (光源) is complete independent
- 2D graphics is a special case of 3D
- Easy to implement by API
 - Set the properties of light, camera and material.
 - To determine the results of image by API.
- Quick hardware implement is supported :OpenGL, Direct 3D etc. is based on this model.



Outline

- Computer Graphics System
- Physical Imaging System
- **Graphics Rendering Pipeline**

Modeling
(Creating 3D Geometry)



Rendering
(Creating, shading images from geometry, lighting, materials)



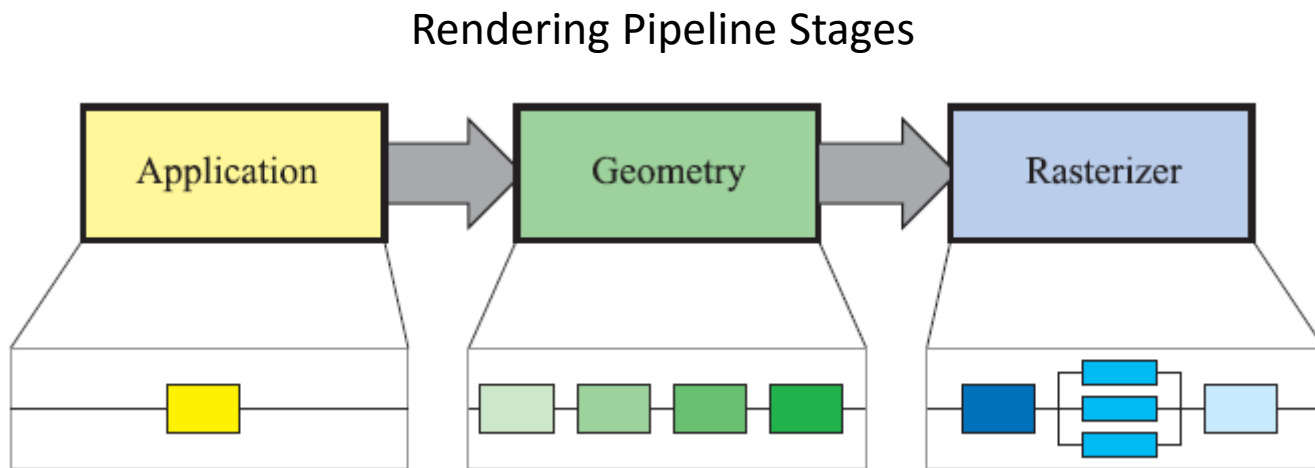
Demo - World War Z

World War Z
VFX Technical Breakdown



Graphics Rendering Pipeline

- What is Rendering?
 - “Rendering is a process that takes as its input a set of objects and produces as its output an array of pixels.”
 - 《Fundamentals of Computer Graphics (3rd Edition)》
- What is the rendering process (Graphic Pipeline)?
 - the sequence of steps used to create a 2D raster representation of a 3D scene.



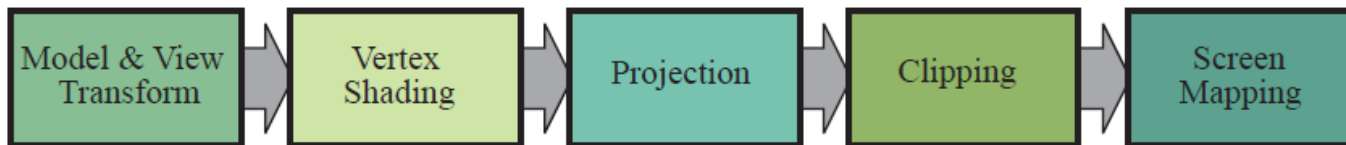
Rendering Pipeline Stages

- **Application**

- e.g. collision detection, global acceleration algorithms, animation, physics simulation..... (On CPU)

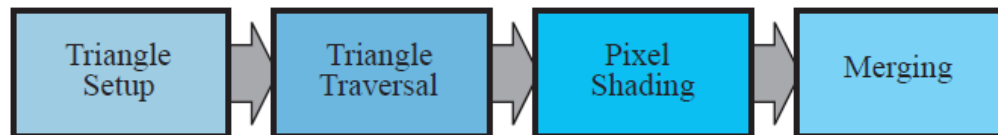
- **Geometry**

- Deal with transforms, projection. Computes what is to be draw, how it should be drawn, and where it should be drawn (On GPU)



- **Rasterizer**

- Conversion from two-dimensional vertices in screen space – each with a z-value (depth value), and various shading information associated with each vertex – into pixels on the screen (On GPU)



Rendering Pipeline

- Abstract model
 - sequence of operations to transform geometric model into digital image
 - graphics hardware workflow
- Underlying API model for programming graphics hardware
 - OpenGL
 - Direct 3D
- Many actual implementations



Direct 3D Samples

The screenshot shows the DirectX Sample Browser interface. At the top, there are navigation links for "DirectX Developer Center", "DirectX SDK Documentation", "DirectX SDK Connect (Submit Feedback)", and "Windows Graphics Documentation". A search bar with "search" and "clear" buttons is also present. On the left side, there are filters for "show" (set to "Direct3D 10") and "sort by" (set to "Date"), along with a checked "Auto-launch documentation" option. The main content area lists four samples:

- 10BitScanout10** (C++, August 2009): Beginner level. Description: "This sample produces a linear gray scale test pattern in both 8 and 10 bit color and displays it on multiple monitors to enable direct comparison." Includes links for "32-bit Executable", "64-bit Executable", "Documentation", and "Install Project".
- DDSWithoutD3DX** (C++, August 2009): Intermediate level. Description: "DDS texture loading without using the D3DX helper functions." Includes links for "32-bit Executable", "64-bit Executable", "Documentation", and "Install Project".
- HDAO10.1** (C++, August 2009): Intermediate level. Description: "This sample, contributed by AMD, presents an innovative technique for achieving High Definition Ambient Occlusion (HDAO). It utilizes Direct3D 10.1 APIs and hardware, making use of the new shader model 4.1 gather4 instruction, to greatly accelerate the performance of this technique." Includes links for "32-bit Executable", "64-bit Executable", "Documentation", and "Install Project".
- TransparencyAA10.1** (C++, August 2009): Intermediate level. Description: "This sample, contributed by AMD, presents a technique for achieving MSAA quality rendering for primitives that require transparency. It utilizes Direct3D 10.1 APIs and hardware to make use of the new fixed MSAA sample patterns, and the export of the coverage mask from the pixel shader." Includes links for "32-bit Executable", "64-bit Executable", "Documentation", and "Install Project".



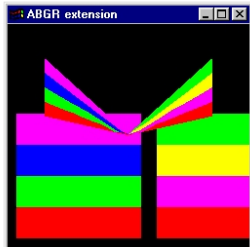
OpenGL Samples

- GLUT demos

https://www.opengl.org/archives/resources/code/samples/glut_examples/examples/examples.html



[examples.zip](#)



Demonstrates the use of the extension EXT_abgr. The same image data is used for both ABGR and RGBA formats in `glDrawPixels` and `glTexImage2D`. The left side uses ABGR, the right side RGBA. The top polygon demonstrates use of texture, and the bottom image is drawn with `glDrawPixels`. Note that the textures are defined as 3 component, so the alpha value is not used in applying the DECAL environment.

Source code: [abgr.c](#).

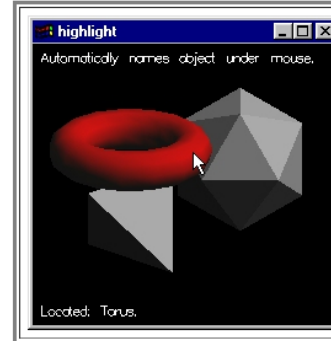
Snapshots: [scene \(shown\)](#).



Arcball like rotation of a chunky dinosaur.

Source code: [dinospin.c](#).

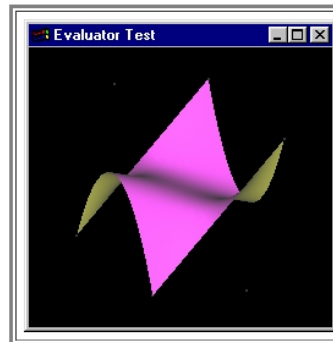
Snapshots: [spinning \(shown\)](#).



This program demonstrates the use of the GL lighting model. Objects are drawn using a grey material characteristic. A single light source illuminates the objects.

Source code: [highlight.c](#).

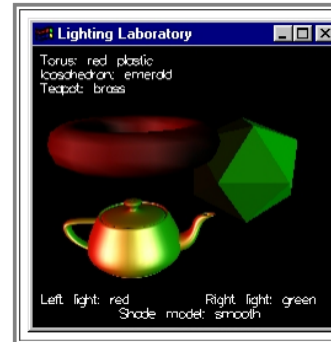
Snapshots: [red torus \(shown\)](#).



OpenGL evaluators simple example with lots of options.

Source code: [evaltest.c](#).

Snapshots: [rotated 3D \(shown\)](#).



Lighting laboratory to experiment with different material properties and lights.

Source code: [lightlab.c](#).

Snapshots: [default \(shown\)](#).



Samples

• NVIDIA GameWorks™ Samples Overview

<https://developer.nvidia.com/gameworks-samples-overview>

NVIDIA GameWorks™ OpenGL Samples

Get the documentation or download the NVIDIA GameWorks™ OpenGL samples here:

[Download >](#)

New Browse or Clone Source from GitHub:

[GitHub >](#)

New samples in 2.0:

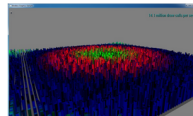
- Blended Antialiasing Sample
- Cascaded Shadow Mapping Sample
- Conservative Rasterization Sample
- Normal-Blended Decal Sample
- Weighted, Blended, Order-independent Transparency Sample

Bindless Graphics Sample

- Category: **Performance**

This sample demonstrates the large performance increase in OpenGL that is made possible by 'Bindless Graphics'. These extensions allow applications to draw large numbers of objects with only a few setup calls, rather than a few calls per object, thus reducing the driver overhead necessary to render highly populated scenery.

[Docs >](#)

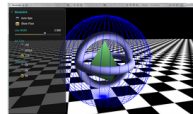


★NEW: Blended AA

- Category: **Performance, Visuals**

This sample implements a two-pass additive blending anti-aliasing technique using Target-Independent Rasterization (TIR), which should give comparable results to MSAA with a reduced memory footprint.

[Docs >](#)

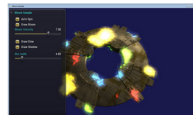


Bloom Sample

- Category: **Visuals**

This sample demonstrates creating a glow effect by post-processing the main scene. It heavily leverages FBO render targets across multiple steps/passes with custom effects processing shaders. It also integrates shadow mapping to demonstrate self-illumination cutting through the shadow effects.

[Docs >](#)



NVIDIA GameWorks™ DirectX Samples

Get the documentation or download the NVIDIA GameWorks™ DirectX samples here.

[Download >](#)

New Browse or Clone Source from GitHub:

[GitHub >](#)

New samples in 1.2:

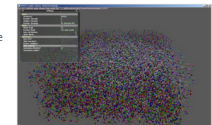
- Antialiased Deferred Rendering
- Motion Blur D3D Advanced Sample

D3D Deferred Contexts Sample

- Category: **Performance**

This sample shows how to use D3D11 Deferred Rendering contexts to lower the CPU overhead and improve performance when rendering large numbers of objects per frame, in situations where instancing is not feasible.

[Docs >](#)

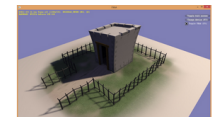


FXAA 3.11 Sample

- Category: **Performance, Visuals**

This sample presents a high performance and high quality screen-space software approximation to anti-aliasing called FXAA.

[Docs >](#)

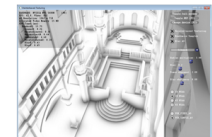


Deinterleaved Texturing Sample

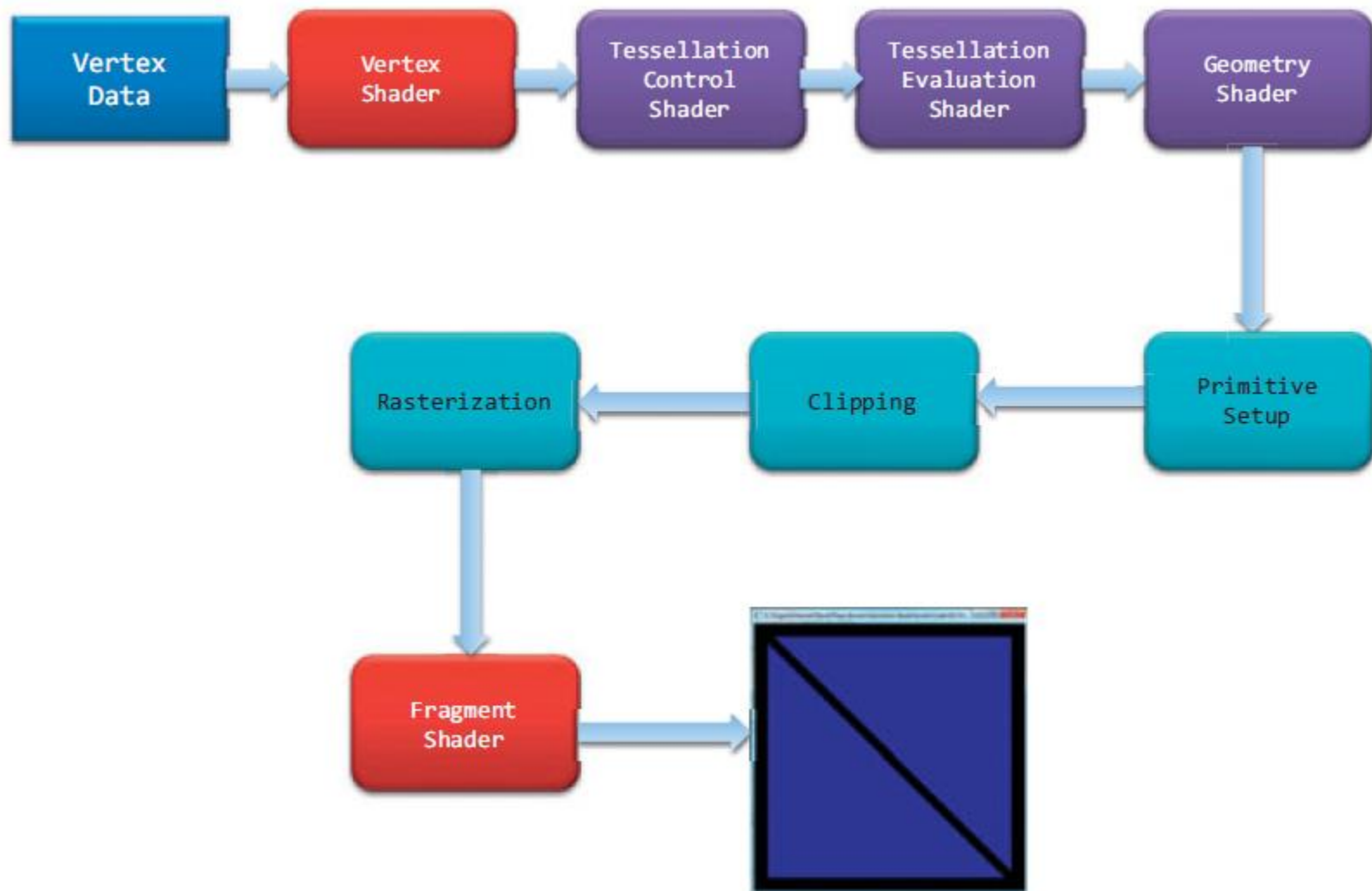
- Category: **Performance, Visuals**

This sample demonstrates how a large, sparse and jittered post-processing filter (here a SSAO pass with a 4x4 random texture) can be made more cache-efficient by using a Deinterleaved Texturing approach.

[Docs >](#)

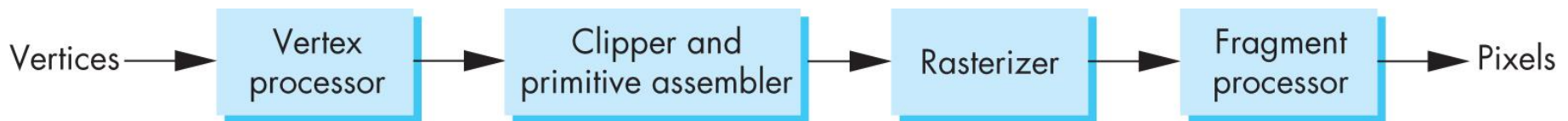


OpenGL Rendering Pipeline

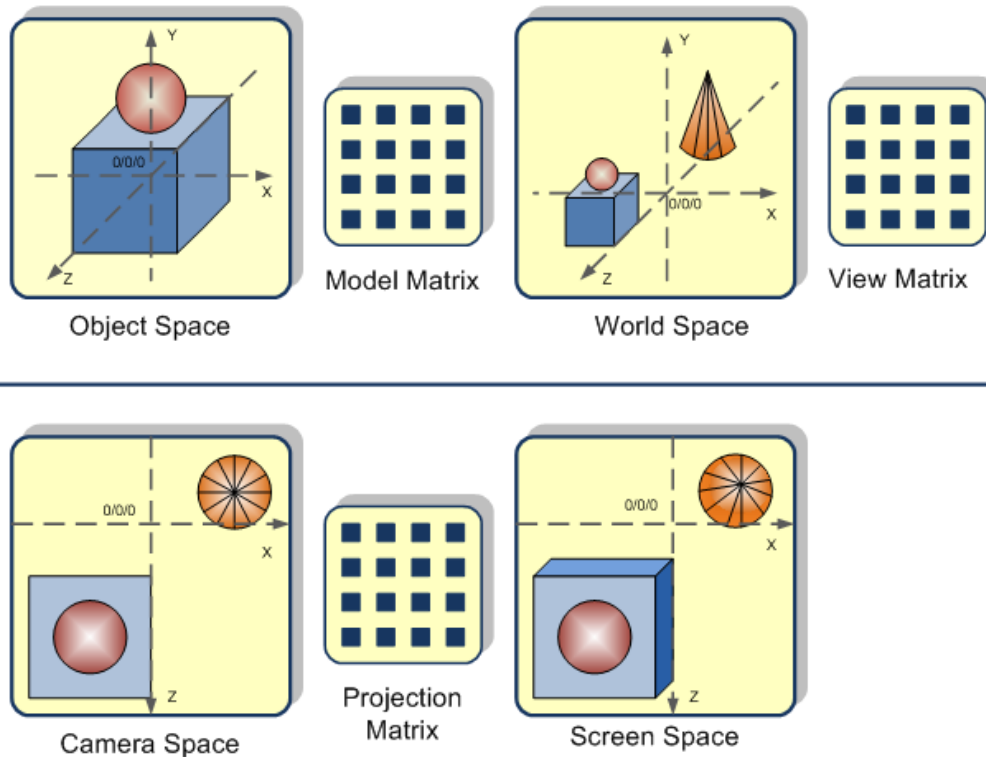


Vertex Processing

- Much of the work in the pipeline is in converting object representations from one coordinate system to another
 - Object coordinates
 - Camera (eye) coordinates
 - Screen coordinates
- Every change of coordinates is equivalent to a matrix transformation



Vertex Processing



1. Vertices of the Object to draw are in **Object space** (as modelled in your 3D Modeller)
2. ... get transformed into World space by multiplying it with the **Model Matrix**
3. Vertices are now in **World space** (used to position the all the objects in your scene)
4. ... get transformed into Camera space by multiplying it with the **View Matrix**
5. Vertices are now in **View Space** – think of it as if you were looking at the scene through “the camera”
6. ... get transformed into Screen space by multiplying it with the **Projection Matrix**
7. Vertex is now in **Screen Space** – This is actually what you see on your Display.



Geometric Primitives

- Different philosophies:

- Collections of complex shapes

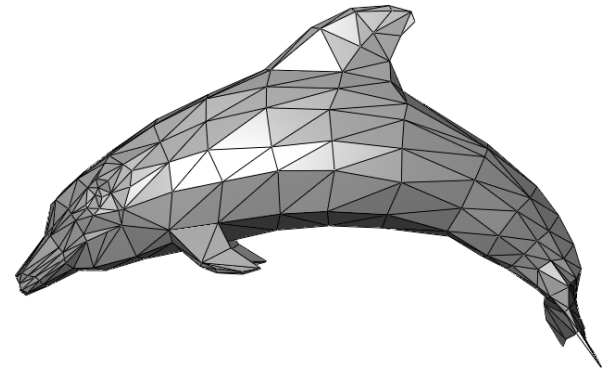
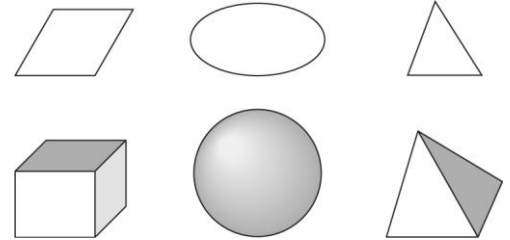
- Spheres, cones, cylinders, tori, ...

- One simple type of geometric primitive

- Triangles or triangle meshes

- Small set of complex primitives with adjustable parameters

- E.g. “all polynomials of degree 2”
 - Splines, NURBS (details in CPSC 424)
 - Implicits

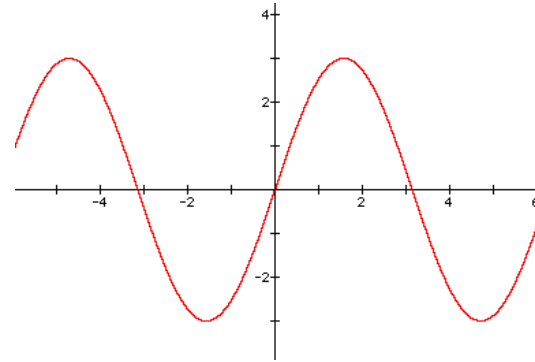


Geometric Primitives

- Explicit Functions

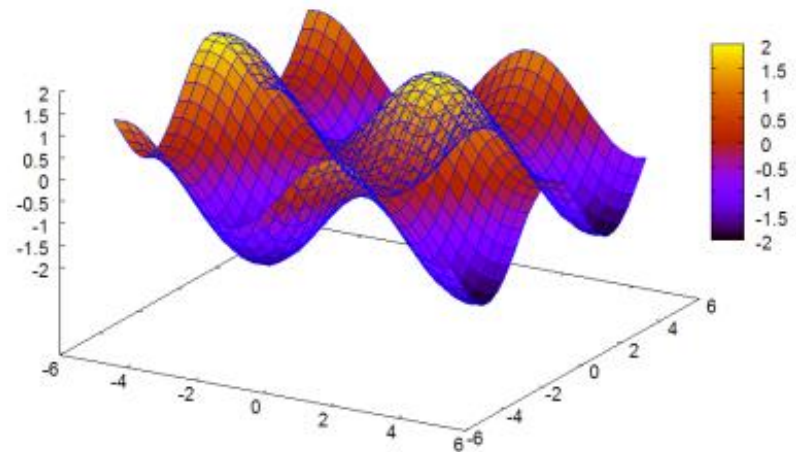
- Curves:

- y is a function of x : $y := \sin(x)$
- Only works in 2D



- Surfaces:

- z is a function of x and y : $z := \sin(x) + \cos(y)$
- Cannot define arbitrary shapes in 3D



Geometric Primitives

- Parametric Functions

- Curves:

- 2D: x and y are functions of a parameter value t
- 3D: x, y, and z are functions of a parameter value t

$$C(t) := \begin{pmatrix} \cos(t) \\ \sin(t) \\ t \end{pmatrix}$$

- Surfaces:

- Surface S is defined as a function of parameter values s, t
- Names of parameters can be different to match intuition

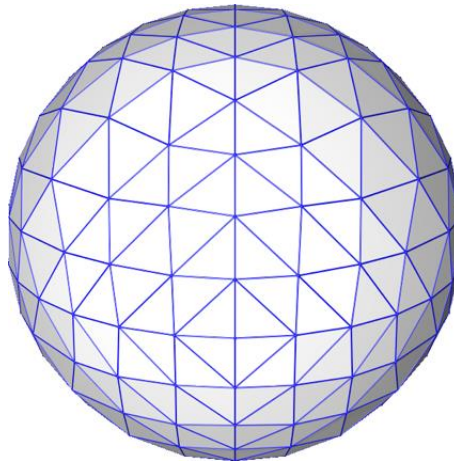
$$S(\phi, \theta) := \begin{pmatrix} \cos(\phi) \cos(\theta) \\ \sin(\phi) \cos(\theta) \\ \sin(\theta) \end{pmatrix}$$



Geometric Primitives

- Implicit Functions
- **Surface:**
 - Surface defined by zero set (roots) of function
 - E.g.

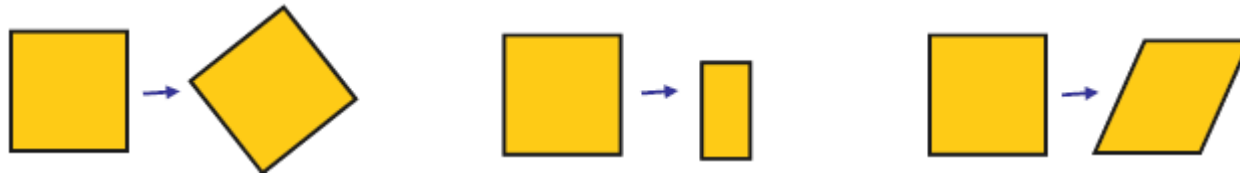
$$S(x, y, z) : x^2 + y^2 + z^2 - 1 = 0$$



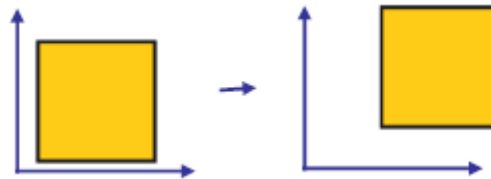
Model/View Transformation

- Types of transformations:

- Rotations, scaling, shearing



- Translations

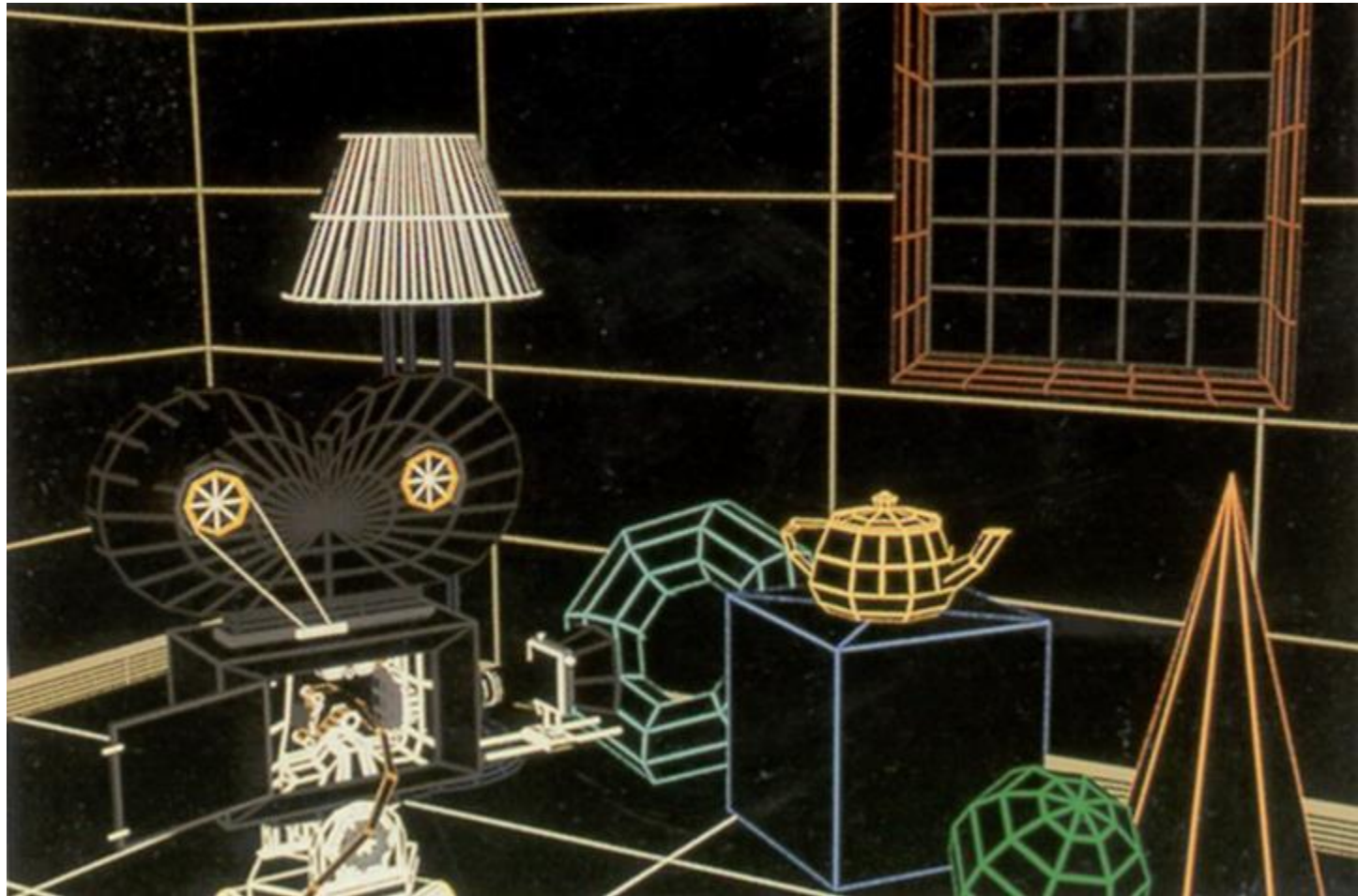


- Other transformations (**not handled by rendering pipeline**)

- Freeform deformation



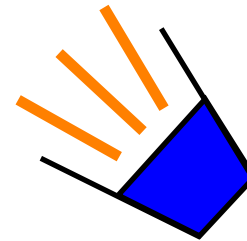
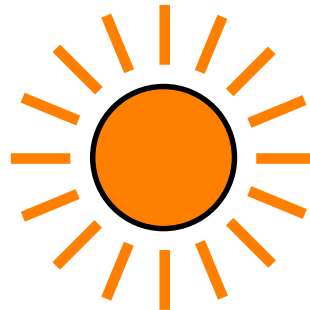
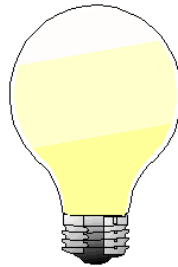
Example - Modeling and Viewing Transformations



Lighting

- Compute brightness based on property of material and light position(s)
- Computation is performed **per-vertex**
- There are several kinds of lights (or light sources)

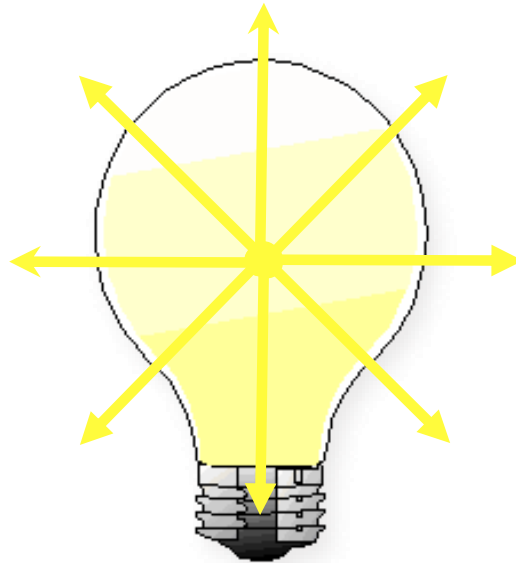
- Light bulbs
- The sun
- Spot Lights
- Ceiling Lights



- These are different because they emit photons (光子) differently

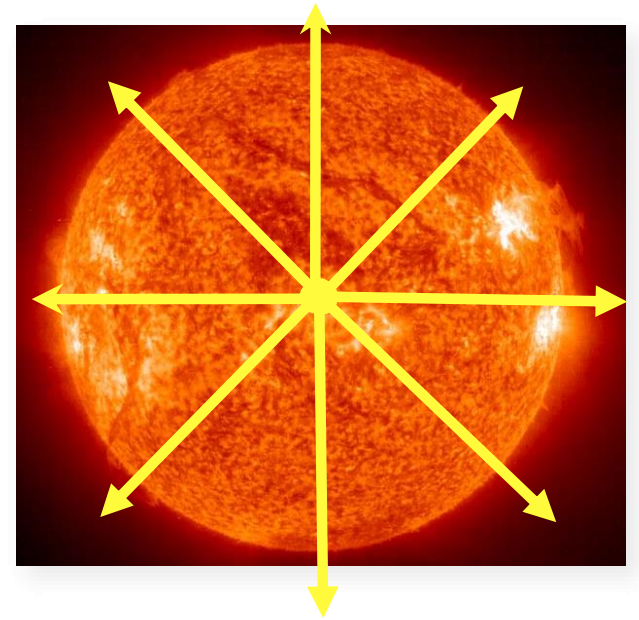
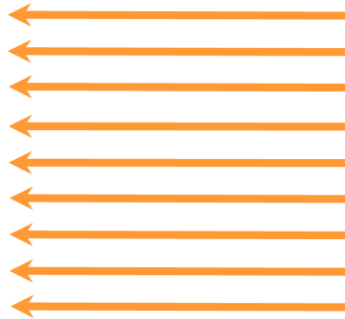
Point Lights (i.e. Light Bulbs)

- Emit light evenly in all directions.
- That is, photons (rays) from a point light all originate from the same point, and have directions evenly distributed over the sphere.



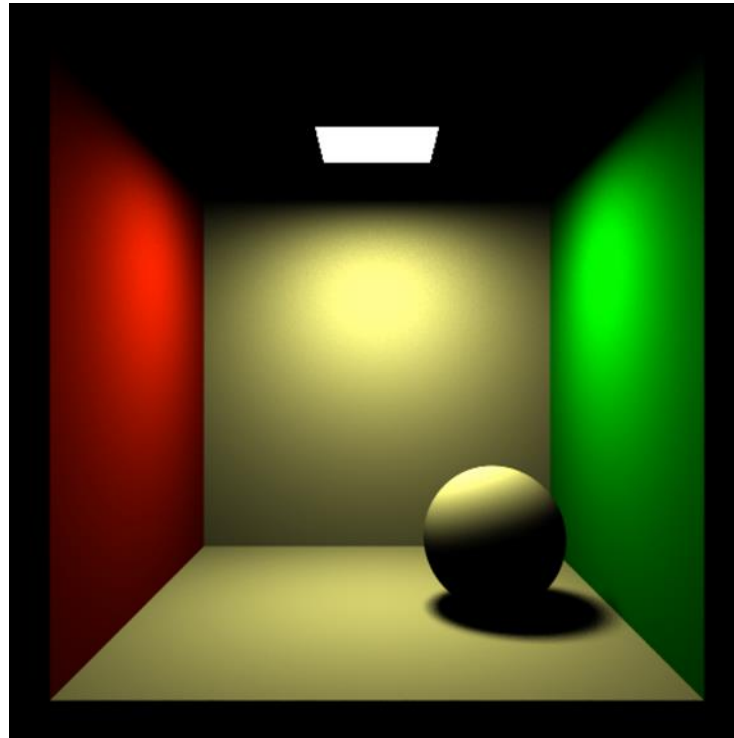
Directional Lights (i.e. the Sun)

- Point light sources at an infinite (or near infinite) distance.
- Can assume that all rays are parallel.

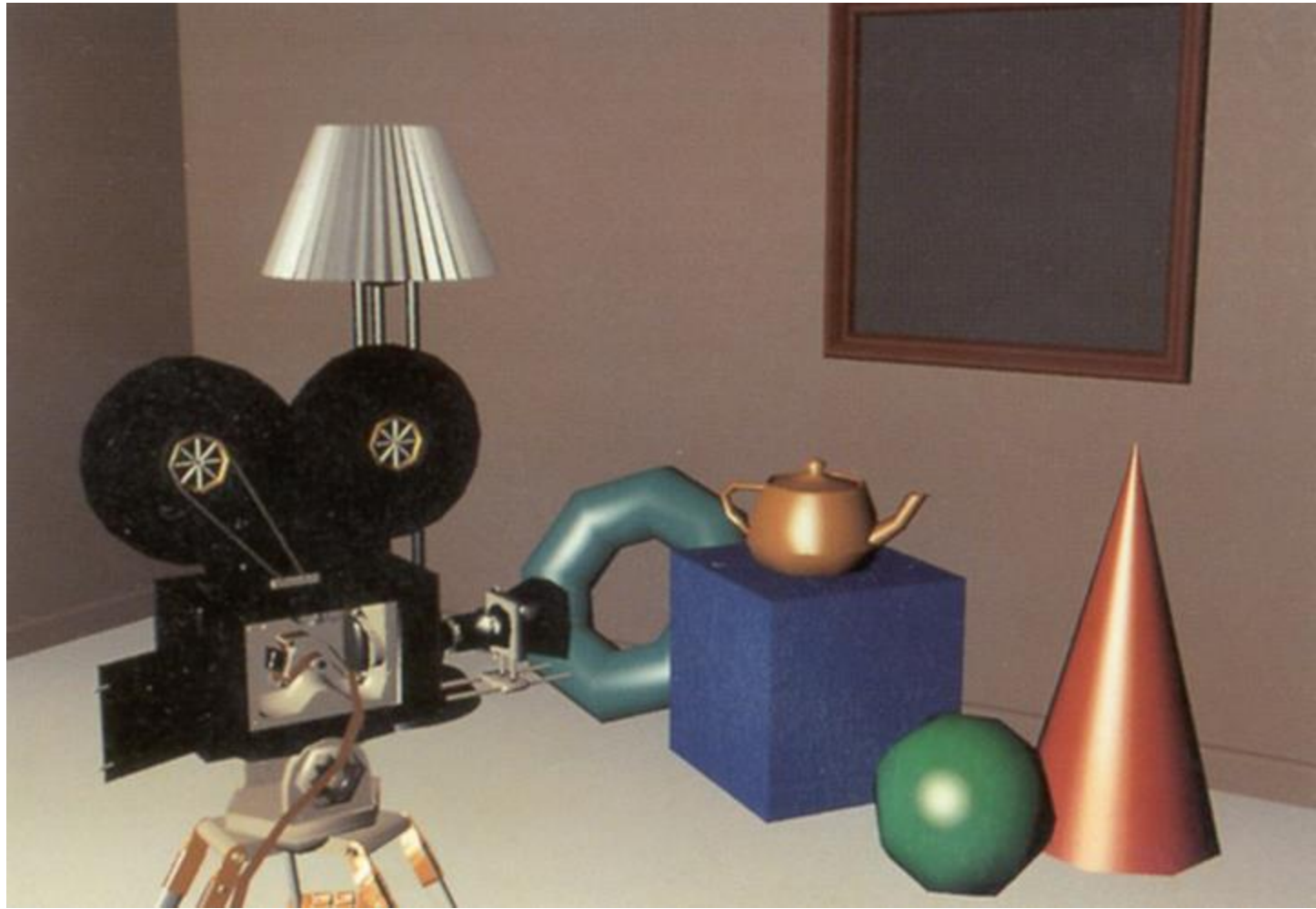


Area Lights (i.e. Ceiling Lights)

- Emits light in every direction from a surface
- Can think of it as a set of point lights, or a patch on which every point is a point light



Example - Lighting



Shading

- Problem: How do we determine the color of a piece of geometry?
- In the real world, color depends on the object's surface color and the color of the light.
- It is the same way in computer graphics.
- “Shading” is the process by which color is assigned to geometry.

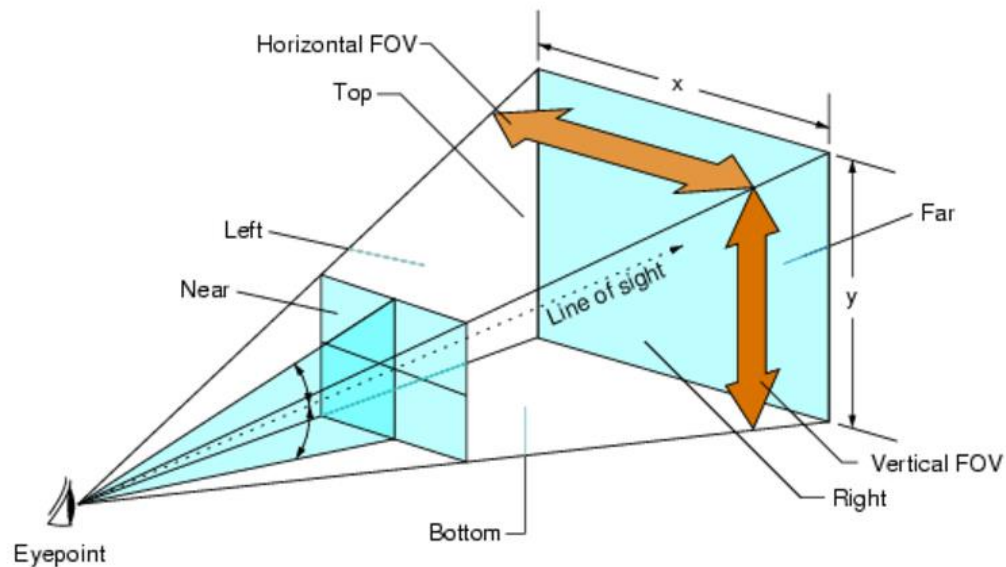


Example - Complex Lighting and Shading



3D to 2D (Projection)

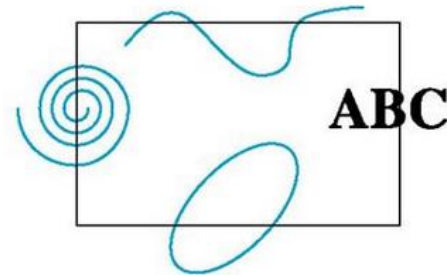
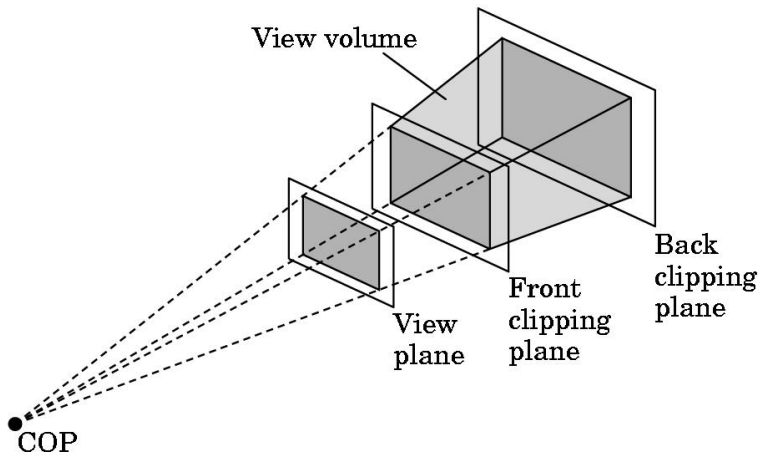
- Problem: The display is, virtually always, only 2D
 - Need to transform the 3D model into 2D
- We do this with a virtual camera
- Represented mathematically by a 3x4 projection (or P) matrix



$$\text{Aspect Ratio} = \frac{y}{x} = \frac{\tan(\text{vertical FOV}/2)}{\tan(\text{horizontal FOV}/2)}$$

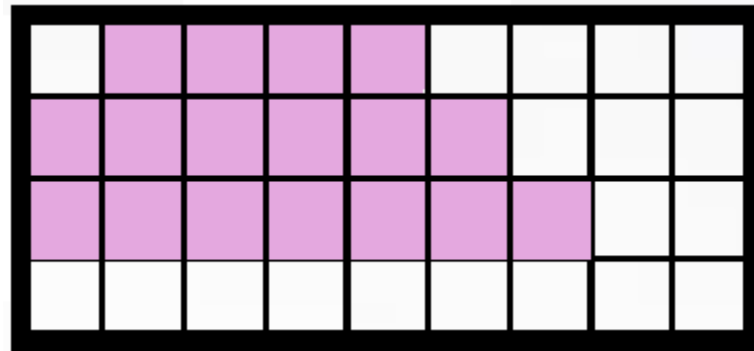
Clipping

- Problem: The camera doesn't see the whole scene
 - In particular, the camera might only see parts of objects
- Solution: Find objects that cross the edge of the viewing volume, and “clip” them
 - Clip: Cut a polygon into multiple parts, such that each is entirely inside or outside the display area



Scan conversion

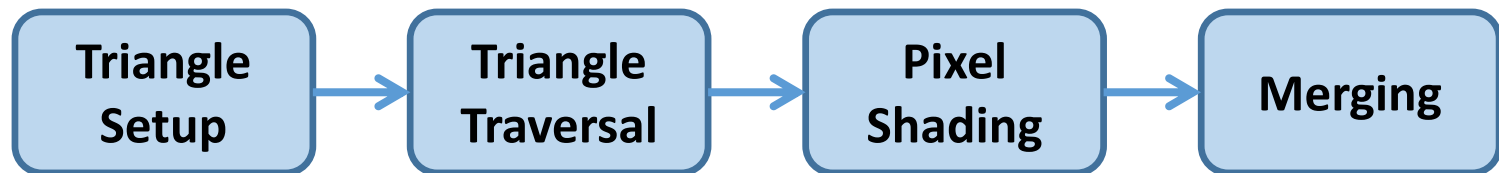
- Convert continuous 2D geometry (lines, polygons etc.) to discrete
- Raster display – discrete grid of elements



Rasterizer Stage

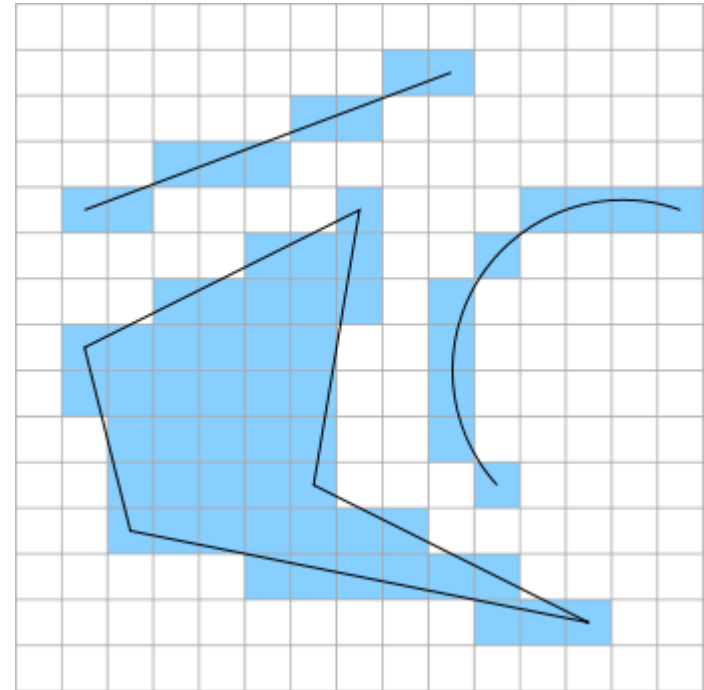
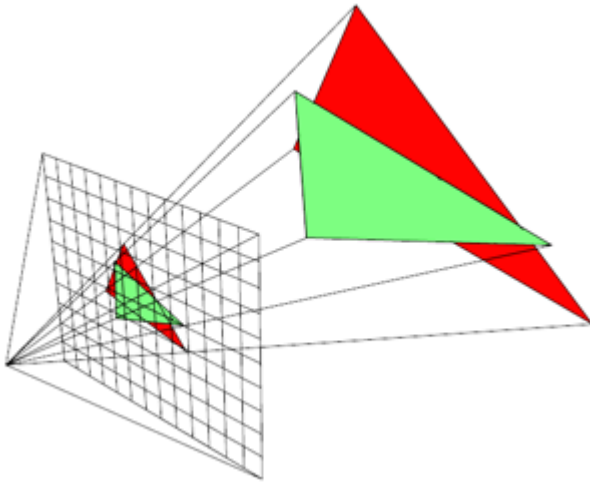
- Rasterizer

- Conversion from two-dimensional **vertices** in screen space – each with a z-value (depth value), and various shading information associated with each vertex – **into pixels** on the screen (On GPU)



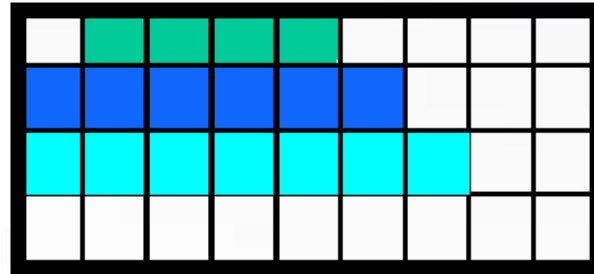
Related Terminology

- Resolution: number of rows & columns in device
- Screen Space: Discrete 2D Cartesian coordinate system of the screen pixels



Texture mapping

- “Gluing (粘合) images onto geometry”
- Color of every fragment is altered by looking up a new color value from an image.



Image



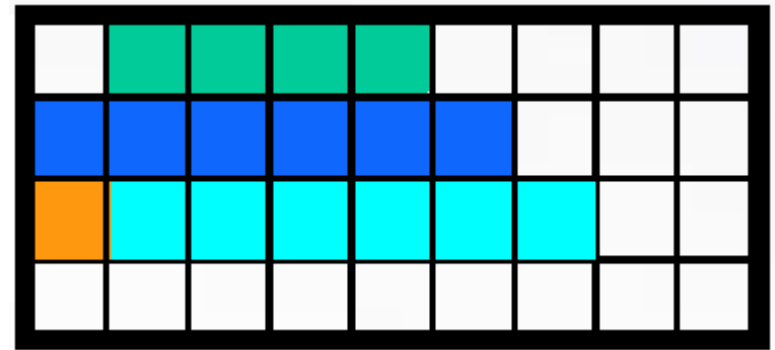
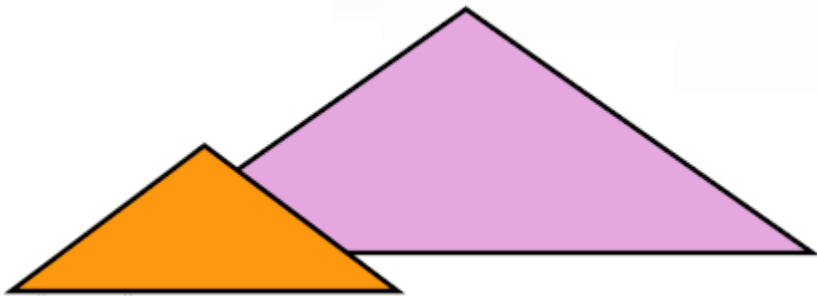
Skin Image

Example – Texture Mapping

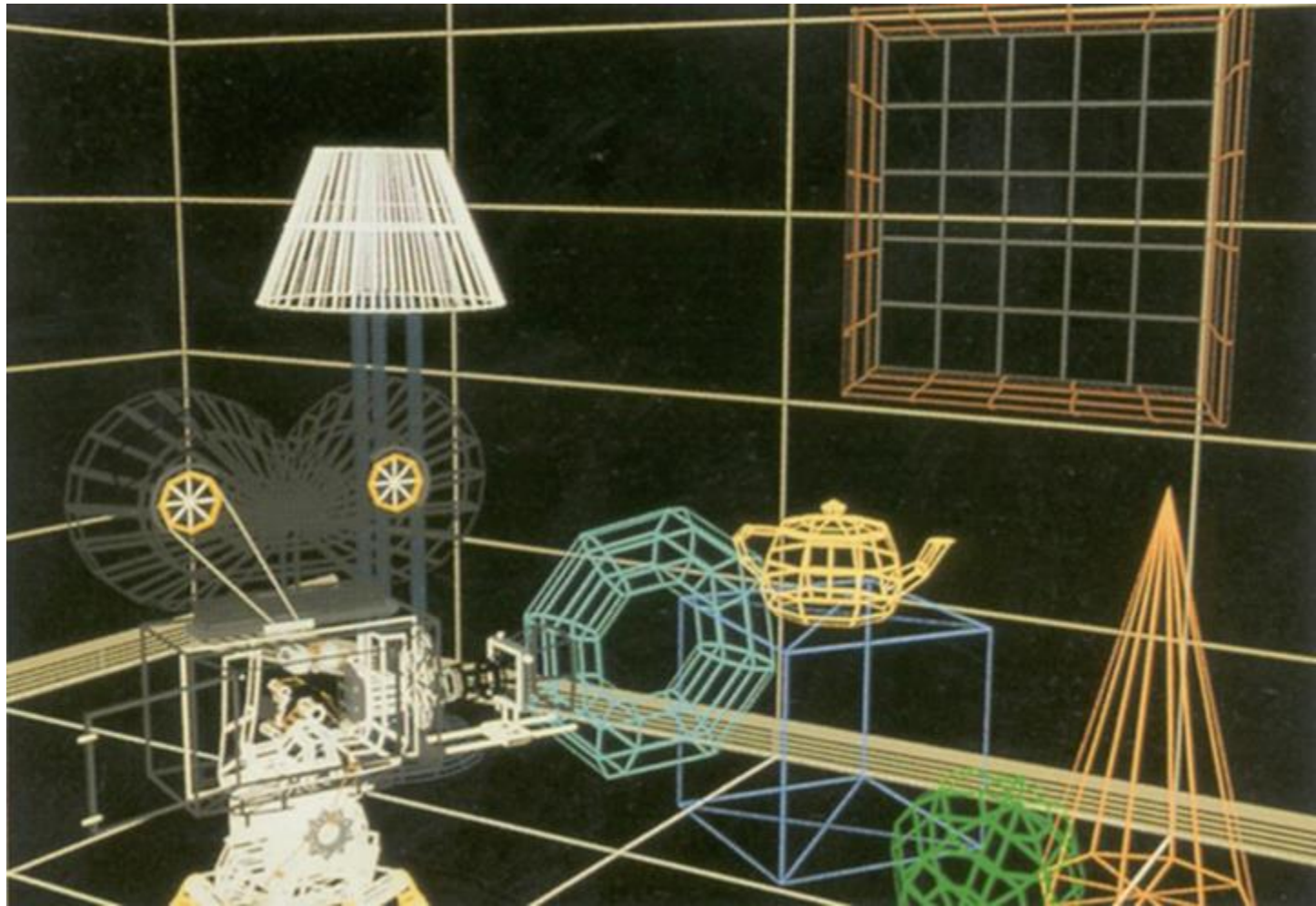


Depth Test

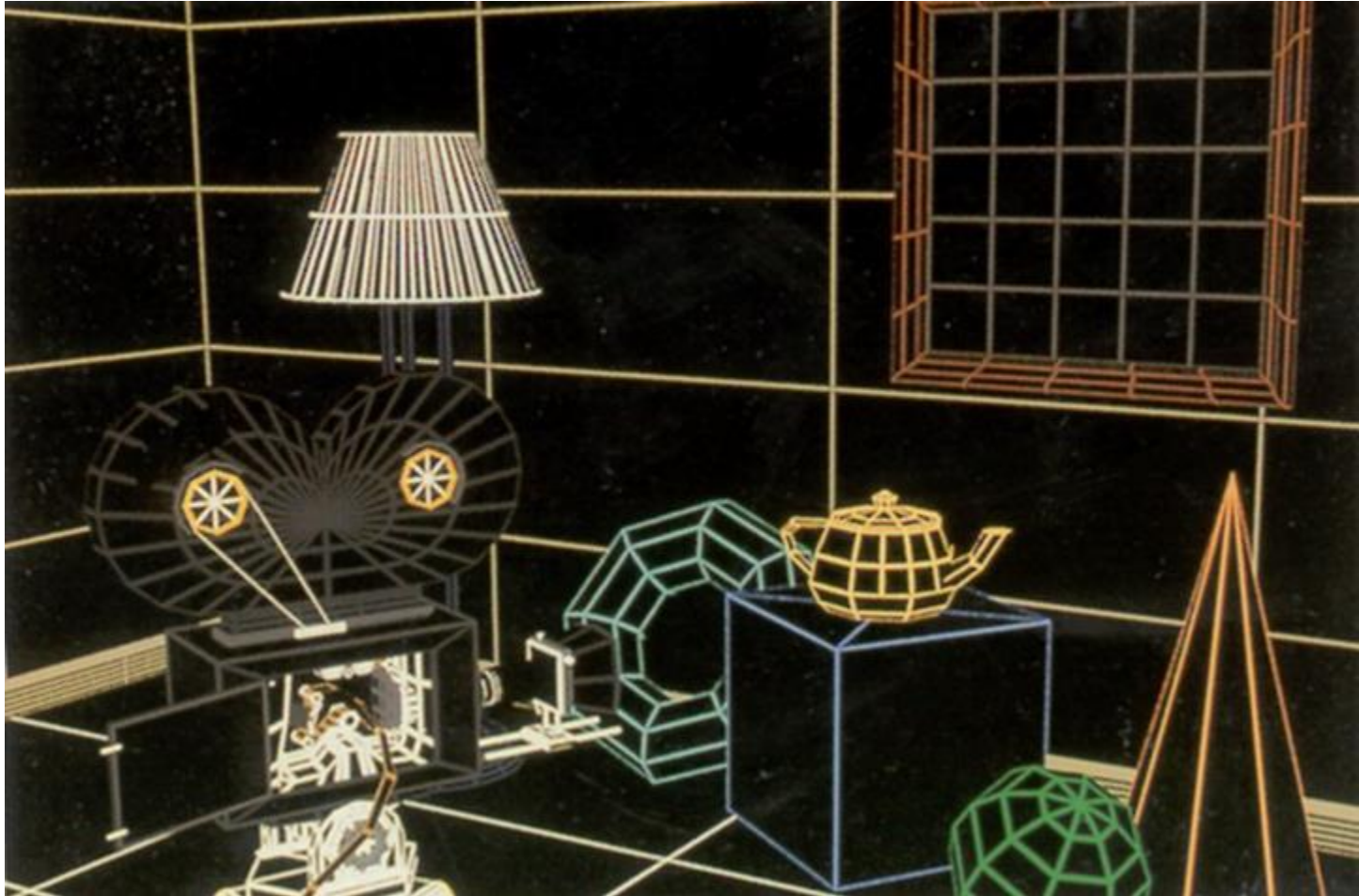
- Remove parts of geometry hidden behind other geometric objects
- Perform on every individual fragment



Example - Without Hidden Line Removal

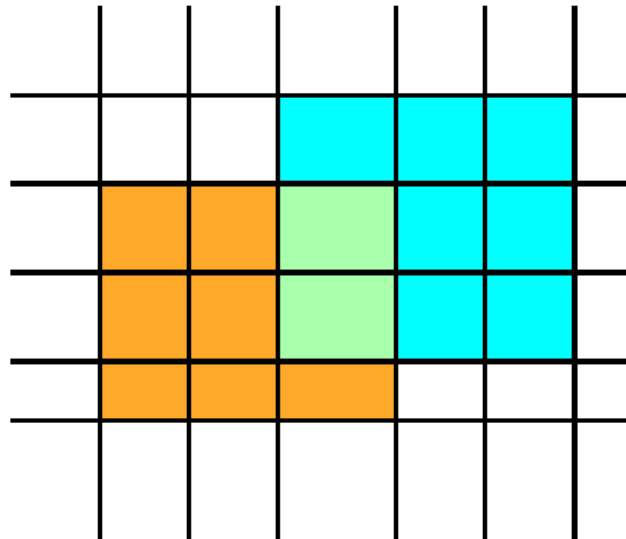


Example - Hidden Line Removal



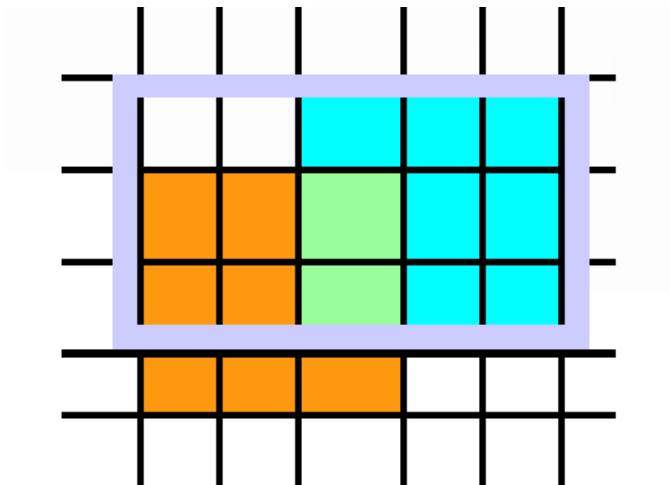
Blending

- final image: write fragments to pixels
- draw from farthest to nearest
 - no blending – replace previous color
 - blending: combine new & old values with arithmetic operations



Frame-buffer

- video memory(图像存储器) on graphics board that holds image
- double-buffering: two separate buffers
 - draw into one while displaying other, then swap to avoid flicker



255	255	0	0	0
255	255	255	255	255
255	255	255	255	255
255	255	155	0	0
155	155	255	255	255
0	0	155	255	255
255	255	155	0	0
155	155	255	255	255
0	0	155	255	255

Modeling vs. Rendering

• Modeling

- Create models
- Apply materials to models
- Place models around scene
- Place lights in scene
- Place the camera

▶ Rendering

Take “picture” with camera

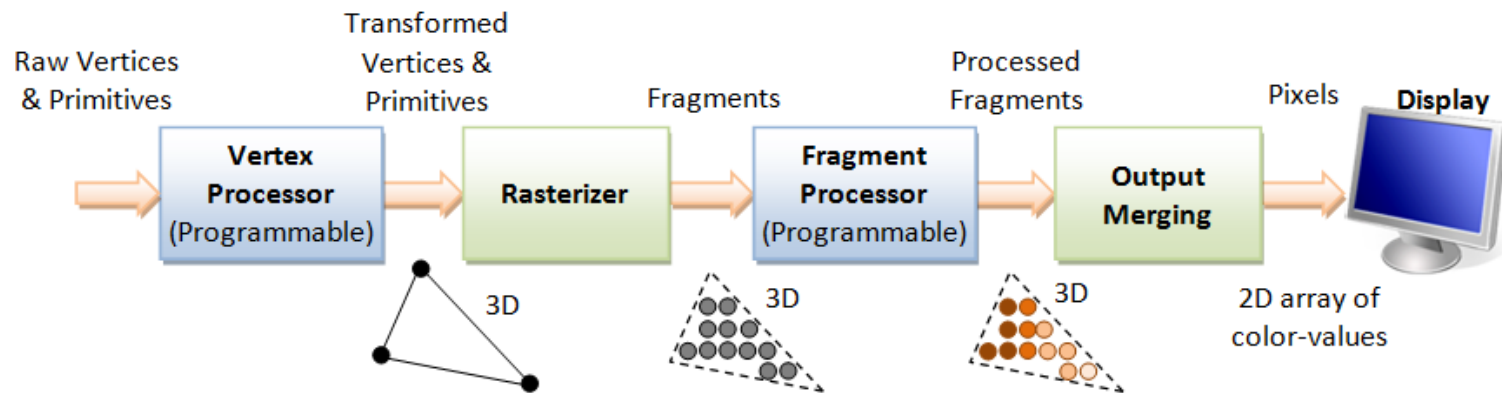
- ▶ Both can be done with commercial software:

Autodesk Maya™, 3D Studio Max™, Blender™, etc



Summary

- The 3D graphics rendering pipeline consists of the following main stages:
 - **Vertex Processing**: Process and transform individual vertices.
 - **Rasterization**: Convert each primitive (connected vertices) into a set of fragments. A fragment can be treated as a pixel in 3D spaces, which is aligned with the pixel grid, with attributes such as position, color, normal and texture.
 - **Fragment Processing**: Process individual fragments.
 - **Output Merging**: Combine the fragments of all primitives (in 3D space) into 2D color-pixel for the display.



3D Graphics Rendering Pipeline: Output of one stage is fed as input of the next stage. A vertex has attributes such as (x, y, z) position, color (RGB or RGBA), vertex-normal (n_x, n_y, n_z) , and texture. A primitive is made up of one or more vertices. The rasterizer raster-scans each primitive to produce a set of grid-aligned fragments, by interpolating the vertices.